

٩. :

ł

đ

÷

UNITED STATES ATOMIC ENERGY COMMISSION CONTRACT W-7405-ENG. 36 This report was prepared as an account of work sponsored by the United States Government. Neither the United States nor the United States Atomic Energy Commission, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness or usefulness of any information, apparatus, product or process disclosed, or represents that its use would not infringe privately owned rights.

> Printed in the United States of America. Available from National Technical Information Service U. S. Department of Commerce 5285 Port Royal Road Springfield, Virginia 22151 Price: Printed Copy \$3.00; Microfiche \$0.95

LA-4800 UC-32 ISSUED: July 1972

i



# TIMEX: A Time-Dependent Explicit Discrete Ordinates Program for the Solution of Multigroup Transport Equations



by

Wm. H. Reed

## CONTENTS

•

\*

٠

.

.

.

ABSTR	TOAS

I.	INTRODUCTION						
11.	THEORY						
	A. One-Dimensional Geometries	2					
	B. Spherical Harmonic Expansion of Source Kernel	2					
	C. Difference Equations	3					
	D. Acceleration Methods	5					
	E. First-Collision Source	8					
	F. Boundary Conditions	10					
	G. Moving Boundaries	11					
111.	PROGRAM DESCRIPTION	11					
	A. Subroutines	11					
	B. Data Storage	13					
	C. Problem Restart	19					
	D. Input/Output Files	20					
IV.	DETAILED INPUT SPECIFICATION	20					
	A. Title Information	21					
	B. Control Parameters	21					
	C. Input Arrays	21					
v.	QUICK REFERENCE INPUT INSTRUCTIONS	25					
VI.	SAMPLE PROBLEM	27					
ACKNO	WLEDGMENT	29					
REFER	ENCES	29					
APPEN	DIX A	30					

### LIST OF TABLES

.

.

•

I.	Analytic Forms of V • Ωψ in Common One- Dimensional Geometries	2
II.	Geometric Functions for One-Dimensional Geometries	4
III.	Analytic Uncollided Flux	9
IV.	TIMEX Subroutines	11
v.	Necessary System Routines	13
VI.	Contents of Blank Common Block IA	13
VII.	Assignment of I/O File Designators	20
VIII.	Options for LASL Formats	20
IX.	Examples of the Use of LASL Formats	21
x.	Structure of Cross-Section Block	22
XI.	ISTART Options	23
XII.	SOURCE Input Options	23
XIII.	IFISS Options	24
XIV.	Sample Mixture Instructions	24
XV.	Time Zone Control Card	25
XVI.	Input Cards for Sample Problem	28

# TIMEX: A TIME-DEPENDENT EXPLICIT DISCRETE ORDINATES PROGRAM FOR THE SOLUTION OF MULTIGROUP TRANSPORT EQUATIONS

### Ъy

### Wm. H. Reed

### ABSTRACT

A finite difference technique is given for solving the one-dimensional (slab, cylindrical, spherical), time-dependent, multigroup transport equations with anisotropic scattering. This technique is unconditionally stable so that arbitrarily large time steps can be taken. Because no iteration is performed the method is exceptionally fast in terms of computing time per time step. Two acceleration methods designed to improve the accuracy of the finite difference technique are presented. Both acceleration methods are available in the TIMEX code, which uses the finite difference technique to solve the time-dependent transport equation in one space dimension. Detailed input and usage instructions for TIMEX are given. A sample problem is presented.

### I. INTRODUCTION

The TIMEX program was designed to solve the time-dependent, multigroup transport equations in one-dimensional geometries. Slab, cylindrical, and spherical geometries are available. All of the features commonly available in one-dimensional, steady-state transport codes were incorporated into TIMEX, with the exception of the various eigenvalue searches that are meaningless in a time-dependent context.

The code produces meaningful results in both wave and diffusion situations. Wave situations are characterized by spatial discontinuities in the neutron flux that propagate with the velocity of the neutrons and are important over short time intervals. A diffusion situation occurs when scattering is important and when the neutron flux is smooth and varies slowly. A typical time-dependent transport problem can involve a progression through a wavelike regime in the beginning to a diffusion situation after all of the wavefronts have left the system of interest.

An instantaneous point source of neutrons in a sphere represents the ultimate in wavefront behavior. Here the solution is a series of shells of neutrons propagating outward with velocities characteristic of each energy group. Inside the outermost shell lies a continuum of neutrons that have suffered one or more collisions. To treat such a difficult problem, a first-collision source option was included in the TIMEX code. Under this option an analytic representation of the uncollided flux is used to generate a source to the collided flux, which is calculated numerically by the code. This approach improves the accuracy of the code in the above situation. A first-collision source is also used to treat instantaneous plane sources in slabs and line sources in cylinders.

Other special features and capabilities of the TIMEX code include:

- (1) Direct or adjoint calculations
- (2) General order scattering anisotropy
- (3) Vacuum, specular reflection, isotropic return, periodic and albedo boundary conditions allowed
- (4) Built-in S<sub>n</sub> constants
- (5) Coarse-mesh problem description
- (6) Input of cross sections from cards or disk file

- (7) Core dump and restart available at selected time steps
- (8) Flexible input for initial condition and inhomogeneous source
- (9) Input of isotropic or anisotropic inhomogeneous distributed sources and boundary sources
- (10) Detailed editing capability
- (11) Input of space-dependent material density
- (12) Ability to load new cross sections, sources, radii, velocities, densities, etc., at selected times
- (13) Time step sizes may differ for each energy group
- (14) Use of either or both of two devices to improve accuracy
- (15) Extensive use of extended core storage to minimize fast core storage requirements.

### II. THEORY

The multigroup neutron transport equations can be written in the form

$$\mathbf{V}^{-1} \frac{\partial \Psi}{\partial t} = -\mathbf{B} \Psi + \mathbf{q} \quad , \tag{1}$$

subject to the initial condition  $\Psi(0) = \Psi_0$ . The vector  $\Psi$  contains the unknown angular fluxes in each energy group as a function of time t, position r, and direction  $\Omega$ . The diagonal matrix V contains the neutron velocities, the vector q contains inhomogeneous sources, and the linear operator **B** takes the standard form

$$\mathbf{B}\Psi = (\mathbf{L} - \mathbf{S})\Psi \tag{2a}$$

$$(L \Psi)_{g} = \Omega \cdot \nabla \Psi_{g} + \sigma(r)\Psi_{g}$$
 (2b)

$$(\mathbf{S} \Psi)_{\mathbf{g}} = \sum_{\mathbf{g}'} \int d\Omega' \ K(\mathbf{r}; \ \mathbf{g}', \Omega' \neq \mathbf{g}, \Omega) \Psi_{\mathbf{g}'}(\mathbf{r}, \Omega').$$
(2c)

The subscript g appearing above denotes the g'th component of subscripted vectors. In what follows we will always order the unknowns  $\Psi_g$ , g = 1, 2, ..., G, so that  $Y_1$  contains the neutrons of highest energy. Appropriate homogeneous boundary conditions for Eq. (1) are assumed to be incorporated into the domain of the operator **B**. Inhomogeneous boundary

conditions must be accounted for in the source term q. (See Sec. II.F. for boundary conditions available in TIMEX.)

In Eqs. (2) the operator L represents the loss mechanisms of the transport equation, and the term  $\Omega \cdot \nabla \Psi_g$ , which could well be written  $\nabla \cdot \Omega \Psi_g$ , represents loss due to neutron streaming. The loss due to scattering and absorption is given by  $\sigma(r)\Psi_g$ , where the total cross section  $\sigma$  is the sum of the scattering and absorption cross sections. The operator **S** represents all homogeneous source mechanisms, therefore the kernel K should be considered to represent both the scattering and fission processes. Details about the assumed form of the kernel K are given in Sec. II.B.

### A. One-Dimensional Geometries

The TIMEX code handles the three standard onedimensional geometries. The operator  $\nabla \cdot \Omega$ is expressed in each of these geometries in Table I. (See also Ref. 1.)

### B. Spherical Harmonic Expansion of Source Kernel

The kernel K of the operator S shown in Eqs. (2) can be represented as the sum of a fission and a scattering contribution, that is,

$$K = K_{\rm F} + K_{\rm S} \quad . \tag{3}$$

The fission kernel is particularly simple and is given by

$$K_{F} = \frac{1}{4\pi} \chi_{gg}(r) v \sigma_{g}^{f}(r)$$
 (4)

In Eq. (4),  $\sigma_g^f$ , is the fission cross section in group g',  $\nu$  is the average number of neutrons

### TABLE I

ANALYTIC FORMS OF  $\nabla \cdot \Omega \Psi$  IN COMMON ONE-DIMENSIONAL GEOMETRIES

Geometry	Variables	
Slab	x,µ	$\mu \frac{9\mathbf{x}}{5\pi}$
Cylindrical <sup>a</sup>	r,µ,ξ	$\frac{\mu}{r} \frac{\partial(r\Psi)}{\partial r} + \frac{\eta}{r} \frac{\partial(\eta\Psi)}{\partial\mu}$
Spherical	r,µ	$\frac{\mu}{r^2} \frac{\partial (r^2 \psi)}{\partial r} + \frac{1}{r} \frac{\partial [(1-\mu^2)\psi]}{d\mu}$
$\frac{1}{\eta} = \sqrt{1 - \mu^2}$	- ξ <sup>2</sup>	

released per fission, and  $\chi_{gg'}$  is the fraction of fission neutrons born in group g due to a fission caused by a neutron in group g'. The function  $\chi$  is normalized so that  $\sum_{g} \chi_{gg'}(r) = 1$  for all r and g'. If  $\chi$  is independent of g' and r, it is referred to as the fission spectrum. The TIMEX code allows the input of a simple fission spectrum or the complete fission matrix. Each of these may in turn be entered by coarse mesh zone, or a single spectrum or matrix may be entered for the entire system.

The scattering kernel is usually more complicated. It is assumed that this kernel can be expanded in spherical harmonics (Legendre polynomials  $P_g$ ) as follows

$$K_{S} = \sum_{\ell=0}^{\text{ISCT}} \frac{2\ell+1}{4\pi} \sigma_{\ell}^{s} (r,g'+g) P_{\ell}(\Omega' \cdot \Omega) \quad . \tag{5}$$

The scattering cross sections  $\sigma_{\ell}^{s}$  must be read in to the code for  $\ell = 0, 1, ..., ISCT$ . The scattering source is then given by (see Eq. (2c))

$$(SY)_{g} = \sum_{g'} \sum_{\ell=0}^{ISCT} \frac{2\ell+1}{2} \sigma_{\ell}^{s}(\mathbf{r},g' \neq g)P_{\ell}(\mu)$$
$$\times \int_{-1}^{1} P_{\ell}(\mu')\Psi_{g'}(\mathbf{r},\mu')d\mu' \qquad (6)$$

in slab and spherical geometry and by a more complicated expression in cylindrical geometry.<sup>2</sup>

### C. Difference Equations

We assume that the phase space under consideration has been divided into a set of mesh cells. Parameters with half-integral subscripts are taken as lying on the boundaries of the mesh cells, and parameters with integer subscripts represent quantities integrated over a mesh cell or "cell-centered" quantities. The spatial grid is then defined by a set of points r  $i+\frac{1}{2}$ 

and the angular grid becomes a set of quadrature points  $\mu_m$  and quadrature weights  $w_m$ . We may think of the quadrature weights as being related to some interval ( $\mu_{1}$ ,  $\mu_{1}$ ), but in practice it is unnec $m-\frac{1}{2}$ ,  $m+\frac{1}{2}$  essary to specify the boundaries  $\mu_{m+\frac{1}{2}}$  of the direcm+ $\frac{1}{2}$ tional cells. In cylindrical geometry the extra angular variable  $\xi$  must be contended with, and the quadrature becomes two dimensional, represented by a set of points ( $\mu_{m}$ ,  $\xi_{m}$ ) on the unit sphere and a set of weights  $w_{m}$ .

The unknowns in the finite-dimensional case are the angular fluxes in all energy groups at the mesh cell centers,  $\psi_{g,m,i}$ , and the mesh cell boundaries,  $\psi_{g,m,i+\frac{1}{2}}$ ,  $\psi_{g,m+\frac{1}{2},i}$ , etc. Here we assume that

$$\psi_{g,m,i} \approx \psi_g(\mu_m, r_i).$$

The source integrals described in Sec. I.B. are computed using the assumed numerical quadrature. The moments of the angular flux are computed as

$$\phi_{g,i}^{\ell} = \sum_{m=1}^{MM} w_m P_{\ell}(\mu_m) Y_{g,m,i}$$
,

where we assume a total of MM directions. The scattering source is then given by

$$s_{g,m,i}^{s} = \sum_{g'} \sum_{\ell=0}^{ISCT} \frac{2\ell+1}{2} \sigma_{\ell}^{s}(r_{i},g' \rightarrow g) P_{\ell}(\mu_{m}) \varphi_{g',i}^{\ell}$$
(7)

in slab and spherical geometries, and by a more complicated expression in cylindrical geometry. The fission source is given by

$$s_{g,m,i}^{f} = \sum_{g'} \frac{1}{2} x_{gg'}(r_{i}) \omega_{g'}^{f}(r_{i}) \varphi_{g',i}^{o}$$
, (8)

and the total source  $\underset{g,m,i}{\text{sources}}$  is obtained by adding the scattering and fission sources

$$S_{g,m,i} = S_{g,m,i}^{s} + S_{g,m,i}^{f}$$
 (9)

The following difference approximation to the g'th member of the set of Eq. (1) is used by the TIMEX code

$$\frac{1}{v} \left( \frac{y^{j+1} - y^{j}}{\Delta v} \right) + \mu_{m} \left( \frac{A_{1} + \frac{y^{j+1}}{2} - A_{1} + \frac{y^{j+1}}{2} - A_{1} + \frac{y^{j+1}}{2} - \frac$$

The area elements for a sphere are not  $4\pi r^2_{1+\frac{1}{2}}$  as would be expected but are defined recursively as indicated in Table II in order to improve the accuracy of the flux near the center of the sphere. The curvature coefficients are also defined in a recursive manner by

$$\alpha_{m+\frac{1}{2}}^{\alpha} - \alpha_{m-\frac{1}{2}}^{\alpha} = \mu_{m} w_{m} \left( A_{1+\frac{1}{2}}^{\alpha} - A_{1-\frac{1}{2}}^{\alpha} \right)$$
(11)

and the starting conditions

$$\frac{\alpha_1 + \alpha}{\frac{1}{2}} = 0 \quad . \tag{12}$$

To solve Eq. (10) for  $y^{j+1}$  given  $y^j$ , it is necessary to make an assumption concerning the shape of the flux over a mesh cell. The "diamond" relations are used in TIMEX; these relations are given by

$$y^{j+1} = \frac{y^{j+1} + y^{j+1}}{2}$$
(13a)

$$y^{j+1} = \frac{y^{j+1} + y^{j+1}}{2} \qquad (13b)$$

where group and some cell-centered subscripts have been deleted. The notations used above are:

The geometric coefficients for the three geometries under consideration are listed in Table II.





If the above relations are used to eliminate  $y_{1+1}^{j+1}$ and  $y_{1-1}^{j+1}$  in Eq. (10), we obtain the following

$$\frac{1}{m+\frac{1}{2}}$$
 in Eq. (10), we obtain the following

equation

$$\left(\frac{v_{\underline{1}}}{v\Delta t}+2\mu_{\underline{m}}A_{\underline{1}+\underline{1}}+\frac{m+\underline{1}}{w_{\underline{m}}}+\sigma_{\underline{1}}v_{\underline{1}}\right)y^{\underline{j+1}}$$

$$= \mu_{m} \left( A_{1 + \frac{1}{2}} + A_{1 - \frac{1}{2}} \right) \gamma_{1 - \frac{1}{2}}^{j+1} + \left( \frac{\alpha_{m + \frac{1}{2}} + \alpha_{m - \frac{1}{2}}}{w_{m}} \right) \gamma_{m - \frac{1}{2}}^{j+1} + \left( \frac{v_{1}}{v_{\Delta t}} \right) \gamma_{1}^{j} + s_{m, 1}^{j} v_{1} + q_{m, 1} v_{1} \quad .$$
 (14)

We use the recursion relation of Eq. (11), which is used to define the  $\alpha$  coefficients, to rewrite Eq. (14) as follows,

$$\begin{bmatrix} \frac{v_{1}}{v\Delta t} + \mu_{m} \left( A_{1+\frac{1}{2}} + A_{1-\frac{1}{2}} \right) + \left( \frac{\alpha_{m+\frac{1}{2}} + \alpha_{-\frac{1}{2}}}{w_{m}} \right) + \sigma_{1} v_{1} \end{bmatrix} y^{j+1}$$

$$= \mu_{m} \left( A_{1+\frac{1}{2}} + A_{1-\frac{1}{2}} \right) y^{j+1}_{1-\frac{1}{2}} + \left( \frac{\alpha_{m+\frac{1}{2}} + \alpha_{-\frac{1}{2}}}{w_{m}} \right) y^{j+1}_{m-\frac{1}{2}}$$

$$+ \left( \frac{v_{1}}{v\Delta t} \right) y^{j} + s^{j}_{m,1} v_{1} + q_{m,1} v_{1} \quad . \tag{15}$$

Equation (15) is used to determine  $y^{j+1}$  from  $y^{j+1}_{j+1}$ ,  $y^{j+1}_{-\frac{1}{2}}$ , and  $y^{j}$  for directions so that  $\mu_{m} > 0$ . When  $m-\frac{1}{2}$   $\mu_{m} < 0$  a similar equation is used to determine  $y^{j+1}_{-\frac{1}{2}}$ ,  $y^{j+1}_{-\frac{1}{2}}$ , and  $y^{j}$ . The diamond difference re  $i+\frac{1}{2}$ ,  $m-\frac{1}{2}$ lations in Eq. (13) are then used to obtain the cell j+1

edge fluxes  $y_{m+\frac{1}{2}}^{j+1}$  and  $y_{m+\frac{1}{2}}^{j+1}$  for  $\mu_m > 0$ , and  $y_{m+\frac{1}{2}}^{j+1}$  and  $y_{m+\frac{1}{2}}^{j+1}$  for  $\mu_m < 0$ .  $1 - \frac{1}{2}$  Use of a diamond relation such as

$$Y_{1+\frac{1}{2}} = 2Y_{1} - Y_{1-\frac{1}{2}}$$

may give rise to negative fluxes. This is likely to occur whenever  $\left(\sigma_{i} + \frac{1}{v\Delta t}\right) V_{i}$  is large. To prevent negative fluxes, a set to zero fixup is used. The cell edge fluxes  $y_{j+1}^{j+1} (y_{j+1}^{j+1} \text{ for } \mu_{m} < 0)$  are tested  $i + \frac{1}{2} i - \frac{1}{2}$ immediately after computation and are set to zero if negative. The cell centered flux  $y_{j+1}^{j+1}$  is then recomputed from Eqs. (10) and (13b) with  $y_{j+1}^{j+1} = 0$  $\left(y_{j+1}^{j+1} = 0 \text{ for } \mu_{m} < 0\right)$  to preserve neutron balance. The cell edge flux  $y_{m+\frac{1}{2}}^{j+1}$  is not tested for positivity because in practice it is rarely negative.

Occasionally the cell centered flux is negative following a set to zero fixup. This is due to the presence of negative sources. Here the fixup attempt is aborted and the originally calculated fluxes are taken as correct.

### D. Acceleration Methods

The two acceleration devices available in the TIMEX code are known as rebalance and extrapolation. The purpose of these devices is to improve the accuracy of the numerical solution. Each method is designed to work properly in most situations, although there are occasions in which the use of one or the other of these devices is specifically reccommended. Both methods are usually stable, but there are certain circumstances under which the use of the rebalance method can lead to an unstable algorithm. These circumstances are discussed later in this section.

1. Exponential Extrapolation. The extrapolation method<sup>3</sup> is derived in the following manner. We assume the equation to be solved is written as

$$V^{-1} \frac{dY}{dt} = BY + q , \qquad (16)$$

where B is a matrix and Y and q are vectors containing the flux and source at all mesh points. The matrix B is a finite difference approximation of the operator **B** shown in Eq. (1). We assume that the flux can be written as

$$\Psi(t) = e^{\omega t} \phi(t) , \qquad (17)$$

where w is a diagonal matrix and the function  $\varphi$  represents a small modulation of the assumed exponential behavior. The function  $\varphi$  obeys the following equation

$$\nabla^{-1} \frac{\mathrm{d}\phi}{\mathrm{d}t} = \mathrm{e}^{-\mathrm{w}t} (\mathrm{B} - \nabla^{-1}_{\mathrm{w}}) \mathrm{e}^{\mathrm{w}t} \phi + \mathrm{e}^{-\mathrm{w}t} \mathrm{q} \quad . \tag{18}$$

Equation (18) is easier to solve than Eq. (16), if  $\phi$  is slowly varying with time. This occurs if the frequencies  $\omega$  are chosen properly. This point is discussed later in this section.

Let us assume that we have a method available for solving Eq. (16). The method of Sec. II.C. is such a method and can be described as follows. The matrix B is split

B = -L + S ,

where L is a matrix representing loss mechanisms and is an approximation of the operator L introduced in Sec. II.A. Similarly, S is a matrix representing the source mechanisms. The method of Sec. II.C. is then formally given by

$$v^{-1}\left(\frac{\underline{y}^{j+1} - \underline{y}^{j}}{\Delta t}\right) = -L \ \underline{y}^{j+1} + S \ \underline{y}^{j} + q \qquad (19a)$$

or

$$\left(\frac{v^{-1}}{\Delta t} + L\right) x^{j+1} = \left(\frac{v^{-1}}{\Delta t} + S\right) x^{j} + q \quad , \tag{19b}$$

The same method is applied to Eq. (18)

$$v^{-1} \frac{\varphi^{j+1} - \varphi^{j}}{\Delta t} = e^{-\omega\Delta t} (-L - v^{-1}\omega_{+}) e^{\omega\Delta t} \varphi^{j+1}$$
$$+ e^{-\omega\Delta t} (S - v^{-1}\omega_{-}) e^{\omega\Delta t} \varphi^{j} + e^{-\omega\Delta t} q,$$
(20)

where the factors  $e^{\omega t}$  have been approximated by their values at the end of the time step.

The matrix w has been split into the components  $w_+$  and  $w_-$ , where  $w_+$  contains all of the positive elements of w,  $w_-$  contains all of the negative elements of w, and  $w = w_+ + w_-$ . The frequencies are split in this manner so that they will always appear as positive quantities in the relevant equations.

Assuming that t = 0 at the beginning of the

step so that  $\phi^{j} = y^{j}$ , we rewrite Eq. (20) as

$$e^{-\omega\Delta t} \left[ \frac{v^{-1}}{\Delta t} + L + v^{-1} \omega_{+} \right] e^{\omega\Delta t} \psi^{j+1}$$
$$= e^{-\omega\Delta t} \left[ \frac{v^{-1}}{\Delta t} + S - v^{-1} \omega_{-} \right] e^{\omega\Delta t} \phi^{j}$$
$$+ e^{-\omega\Delta t} q \quad .$$

Because  $y^{j+1} = e^{\omega \Delta t} \phi^{j+1}$ , we have

$$\frac{\mathbf{v}^{-1}}{\Delta t} + \mathbf{L} + \mathbf{v}^{-1} \mathbf{\omega}_{+} \Big] \mathbf{v}^{\mathbf{j}+1}$$
$$= \left[ \frac{\mathbf{v}^{-1}}{\Delta t} + \mathbf{S} - \mathbf{v}^{-1} \mathbf{\omega}_{-} \right] \mathbf{e}^{\mathbf{\omega} \Delta t} \mathbf{v}^{\mathbf{j}} + \mathbf{q} \quad . \tag{21}$$

Equation (21) is similar to Eq. (19b). In Eq. (21) the flux at the beginning of the time step is scaled by the factor  $e^{\omega\Delta t}$  and the terms  $V^{-1}\omega_{+}$  and  $V^{-1}\omega_{-}$  are added to the matrices L and S. Because  $V^{-1}\omega_{+}$  is diagonal, it suffices to add this term to the total cross section, which appears on the diagonal of L. Thus, the algorithm for solving Eq. (19b) for  $Y^{j+1}$  can be used with minor modification to solve Eq. (21).

The frequencies w are altered after each time step to obtain the best accuracy. A good, practical choice for these frequencies seems to be given by

$$w_j = \frac{1}{\Delta t} \ln \left( \frac{\gamma j}{\gamma j - 1} \right) ,$$
 (22)

where the division is performed componentwise. The frequencies w, are then used in Eq. (21) to obtain the flux  $y^{j+1}$ . If in Eq. (22) the flux is zero at some points, the frequencies are set to zero at those points.

It is unnecessary to allow the frequencies to depend on angle, energy, and space to obtain a significant increase in the accuracy of the code. In practice, the TIMEX code allows energy and spacedependent frequencies only. The extrapolation method is a special kind of predictor-corrector method and is especially appropriate in situations where the time variation of the flux is smooth and nearly exponential. This condition is always true at long times following some initial transient if the cross sections and sources remain constant with time. It has been experimentally observed that, for long times following some perturbation in a system, the above frequencies converge to a single number that is an approximation to the inverse of the asymptotic period of the system.

2. Rebalance. The second acceleration method available in the TIMEX code is more appropriate to situations in which the flux changes rapidly than is the extrapolation method. Let us assume that we are solving Eq. (16) using the method of Eq. (19a). This method, as it stands, is inaccurate. The lack of accuracy is due to the splitting of the matrix B, so that the loss mechanisms are taken as proportional to the flux at the new time and the sources are proportional to the fluxes at the old time. The resulting inbalance between sources and losses prevents the computed flux from following transients as rapidly as it should.

A more accurate scheme is the first-order accurate fully implicit method

$$v^{-1} \frac{y^{j+1} - y^{j}}{\Delta t} = B y^{j+1} + q , \qquad (23)$$

or the second-order accurate Crank-Nicholson method

$$V^{-1} \frac{\Psi^{j+1} - \Psi^{j}}{\Delta t} = B\left(\frac{\Psi^{j+1} + \Psi^{j}}{2}\right) + q \qquad (24)$$

The Crank-Nicholson method is equivalent to a diamond difference assumption in the time variable. These two schemes are unconditionally stable, so that large time steps can be taken. Unfortunately, to advance the solution by one time step the full matrix B must be inverted. This is equivalent to the solution of a steady-state transport problem, and iterative procedures must be used. These iterative processes can be slowly convergent so that a large amount of computation is expended in the coarse of a single time step. Modern convergence acceleration devices such as coarse-mesh rebalance<sup>4</sup> can reduce this computation significantly.

It is our purpose to describe how this acceleration device can be applied in a different manner to improve the accuracy of the difference scheme of Eq. (19). In what follows we will deal exclusively with a one-group problem, and the matrices L and S must be considered as representing a single group of neutrons. In TIMEX the coarse-mesh acceleration device is applied to each group individually, with sources from other groups treated as constants. Given the flux at time level j, we calculate a first approximation  $\tilde{Y}^{j+1}$  to the flux  $Y^{j+1}$  at time level j+1 from Eq. (19) in the following manner:

$$\left(\frac{\underline{v}^{-1}}{\Delta t} + L\right)\widetilde{Y}^{j+1} = \left(\frac{\underline{v}^{-1}}{\Delta t} + S\right)Y^{j} + q \quad .$$
 (25)

The flux  $y^{j+1}$  is then assumed to be represented as

$$\mathbf{y}^{j+1} = \sum_{i} \mathbf{f}_{i} \quad \mathbf{\tilde{y}}_{i}^{j+1} \quad , \tag{26}$$

where the vectors  $\widetilde{Y}_{1}^{j+1}$  contain the elements of  $\mathfrak{P}^{j+1}$  corresponding to the i'th spatial mesh cell and are zero elsewhere. Fluxes on the boundary between mesh cells i and i+l are included with  $\widetilde{\gamma}_4^{j+1}$ for directions so that  $\mu_m > 0$ , and with  $\widetilde{Y}_{i+1}^{i+1}$  for directions so that  $\mu_m < 0$ . The parameters  $f_i$ are called rebalance factors. To determine these factors, and therefore the desired flux  $y^{j+1}$ , we insert the expression on the right-hand side of Eq. (26) into Eq. (23) and integrate over all directions (that is, multiply by  $w_m$  and sum over all m). The integrals can be performed because the  $\mu$  dependence of  $y^{j+1}$  is specified by Eq. (26). The result of this integration is a set of equations for the rebalance factors f .. This set of equations is written as

$$\begin{pmatrix} -FL_{1+\frac{1}{2}}^{j+1} \\ f_{1+\frac{1}{2}} \end{pmatrix} f_{1+1} + \begin{pmatrix} AB_{1}^{j+1} + FL_{1-\frac{1}{2}}^{j+1} + FR_{1+\frac{1}{2}}^{j+1} \\ f_{1-\frac{1}{2}} \\ f_{1-1} = Q + \frac{\varphi^{j}V_{1}}{v\Delta t} \quad .$$
 (27)

In Eq. (27) the quantities  $FL_{i+\frac{1}{2}}^{j+1}$  and  $FR_{i+\frac{1}{2}}^{j+1}$  are the  $i+\frac{1}{2}$   $i+\frac{1}{2}$ left and right flows across the cell face at  $i+\frac{1}{2}$  computed from  $\tilde{Y}^{j+1}$  as

$$\operatorname{FL}_{\substack{j+1\\ i+\frac{1}{2}}}^{j+1} = \sum_{m} |\mu_{m}| \widetilde{Y}_{m}^{j+1} w_{m}, \quad \mu_{m} < 0$$

$${\rm FR}_{1+\frac{1}{2}}^{j+1} = \sum_{m} |\mu_{m}| \widetilde{\mathbb{Y}}_{m}^{j+1} w_{m}, \ \mu_{m} > 0 .$$

The quantity  $AB_{i}^{j+1}$  is the total absorption in the i'th cell augmented by the term  $\frac{\widetilde{\phi}^{j+1}V_{i}}{v\Delta t}$ , where  $\widetilde{\phi}^{j+1}$ is the scalar flux given by  $\widetilde{\phi}^{j+1} = \int \widetilde{\psi}^{j+1} d\mu$ . The above equations for the rebalance factors are tridiagonal and are easily solved. Having solved for these factors, we obtain the flux at the time level j+1 from Eq. (26).

It is possible to insert Eq. (26) into Eq. (24) and integrate over all directions to obtain a set of equations for the rebalance factors. These equations are again tridiagonal in form, but they also involve flows and absorptions at the previous time level. The resulting method gives answers that are more accurate than if the rebalance factors were obtained from Eq. (27). However, there is an increased danger of instability when the rebalance factors are obtained from the Crank-Nicholson method. Therefore, the rebalance factors are calculated from Eq. (27) in the TIMEX code.

### E. First-Collision Source

In some transport problems the exact flux at an instant of time involves Dirac delta functions. For example, such functions are obtained for an instantaneous point burst of neutrons at time zero. The accurate prediction of such irregular functions is quite difficult with standard finite difference methods, so that exceedingly fine meshes are required. To circumvent this difficulty, a firstcollision source option is provided in the TIMEX code. This option is selected by setting INSTART equal one and is restricted to the treatment of instantaneous sources located at the origin of the coordinate system, that is, point sources in slab geometry, line sources in cylindrical geometry, and plane sources in slab geometry. The angular dependence of the source neutrons is assumed to be given by  $\delta(\mu - 1)$  in all three geometries, so that in each case the neutrons are assumed to stream directly away from the origin.

If the first-collision source option is specified, the neutron flux is considered as the sum of two terms, the flux due to neutrons that have suffered no collisions (the uncollided flux) and the flux due to neutrons that have suffered one or more collisions (the collided flux). We define the two functions  $\Psi_u$  and  $\Psi_c$  to be the uncollided and collided fluxes, respectively, so that the total flux  $\Psi$  is given by  $\Psi = \Psi_u + \Psi_c$ . These two functions are assumed to obey the two equations

$$\frac{1}{v}\frac{\partial \bar{y}_{u}}{\partial t} + L \bar{y}_{u} = q$$
(28a)

and

$$\frac{1}{v}\frac{\partial \mathbf{Y}_{c}}{\partial t} + L \mathbf{Y}_{c} = S(\mathbf{Y}_{u} + \mathbf{Y}_{c}) \quad . \tag{28b}$$

Equation (28a) is easy to solve analytically for  $Y_{u}$  because there are no scattering sources. When  $Y_{u}$  has been obtained, Eq. (28b) can be solved with difference methods derived earlier. We note that the sum of Eqs. (28a) and (28b) gives

$$\frac{1}{v}\frac{\partial}{\partial t}(\mathbf{y}_{u} + \mathbf{y}_{c}) + L(\mathbf{y}_{u} + \mathbf{y}_{c}) = S(\mathbf{y}_{u} + \mathbf{y}_{c}) + q$$

or

$$\frac{1}{v}\frac{\partial v}{\partial t} + L \ v = S \ v + q \quad , \tag{29}$$

which is the full transport equation for the complete angular flux ¥.

The rationale for splitting the angular flux into collided and uncollided components is that the function  $\Psi_c$  is smoother than  $\Psi_u$ . Because we are solving Eq. (28a) by analytic methods, a non-smooth solution does not cause concern. All errors in the calculation are introduced in the solution

of Eq. (28b) for the collided flux. Because  $Y_c$  is smooth, these errors will be smaller than those involved in the direct solution of Eq. (29) by difference methods.

The analytic uncollided fluxes due to the sources mentioned above are presented in Table III for a single group of neutrons with velocity v. In the following we deal exclusively with a single energy group; all groups are treated in the same manner.

The quantities N<sub>o</sub> shown in Table III for slab, cylinders and spheres are the total number of source neutrons emitted per unit area, the total number of neutrons per unit length, and the total number of neutrons, respectively.

To calculate the source in Eq. (28b) due to the uncollided flux, we need the spherical harmonic moments of the uncollided flux. In slab and spherical geometry these moments are given by

$$\phi_{\boldsymbol{\ell}}(\mathbf{r},\mathbf{t}) = \int_{-1}^{+1} d\mu P_{\boldsymbol{\ell}}(\mu) \boldsymbol{y}_{u}(\mu)$$

Because  $Y_{u}$  involves the delta function  $\delta(1 - \mu)$ , and because  $P_{\ell}(1) = 1.0$  for all the Legendre polynomials, all of the above moments are identical. In cylindrical geometry the spherical harmonics  $Y_{\ell}^{\beta}(\mu, \eta)$ are used instead of the Legendre polynomials. We have

$$\mathbf{Y}_{\boldsymbol{\xi}}^{\boldsymbol{\beta}}\Big|_{\boldsymbol{\mu}=1} = \begin{cases} 1.0 \quad \boldsymbol{\beta}=0\\ \\ 0.0 \quad \boldsymbol{\beta}\neq 0 \end{cases}$$

so that only the  $Y^{0}_{\underline{\ell}}$  moments of the uncollided flux are nonzero. As above, all the  $Y^{0}_{\underline{\ell}}$  moments are identical. For this reason we need only to calculate the zeroth moment of the flux in all three geometries. These moments can always be obtained from the uncollided flux in Table III by omitting the factor  $\delta(1 - \mu)$ .

We next define an appropriate average  $\varphi_{i}^{j}$  of the zeroth moment of the uncollided flux over a time step  $\Delta t_{j}$  and over a cell volume  $V_{i}$ . In spherical geometry we have

# TABLE IIIANALYTIC UNCOLLIDED FLUXGeometrySourceUncollided FluxSlab $N_0\delta(x)\delta(1-\mu)\delta(t)$ $N_0e^{-\int_0^x \sigma(x')dx'}\delta(t-\frac{x}{v})\delta(1-\mu)$ Cylindrical $\frac{N_0\delta(r)\delta(1-\mu)\delta(t)}{2\pi r}$ $\frac{N_0e^{-\int_0^x \sigma(r')dr'}\delta(t-\frac{r}{v})\delta(1-\mu)}{2\pi r}$ Spherical $\frac{N_0\delta(r)\delta(t)}{4\pi r^2}$ $\frac{N_0e^{-\int_0^x \sigma(r')dr'}\delta(t-\frac{r}{v})\delta(1-\mu)}{4\pi r^2}$

 $(\sigma = total cross section)$ 

$$\varphi_{1}^{j} = \frac{1}{\overline{v}_{1}\Delta t} \int \frac{r_{1+\frac{1}{2}}}{r_{1-\frac{1}{2}}} 4\pi r^{2} dr \int \frac{t+\Delta t}{t} dt \varphi_{0}(r,t)$$

$$= \frac{1}{V_{i}\Delta t} \int_{r_{i}-\frac{1}{2}}^{r_{i}+\frac{1}{2}} 4\pi r^{2} dr \int_{t}^{t+\Delta t} dt$$

$$x \frac{\frac{N_{o}e^{-\int_{0}^{r} \sigma(r')dr''}}{\delta(t-\frac{r}{v})}}{4\pi r^{2}}$$

$$= \frac{N_o}{V_1 \Delta t} \int_{r_1 - \frac{1}{2}}^{r_1 + \frac{1}{2}} dr \int_{t}^{t + \Delta t} dt e^{-\int_{0}^{r_0} \sigma(r') dr'} \delta(t - \frac{r}{v})$$

$$\phi_{\mathbf{i}}^{\mathbf{j}} = \frac{N_{\mathbf{o}}}{V_{\mathbf{i}}\Delta t} \int_{\mathbf{r}}^{\mathbf{r}} \mathbf{i} + \frac{1}{2} d\mathbf{r} e^{-\int_{\mathbf{o}}^{\mathbf{r}} \mathbf{o}(\mathbf{r}') d\mathbf{r}'}$$
$$\mathbf{i} - \frac{1}{2}$$

$$x [U(r - vt) - U(r - vt - v\Delta t)]$$

where U(x) is the step function defined by

$$U(\mathbf{x}) = \begin{cases} 0, & \mathbf{x} < 0 \\ 1, & \mathbf{x} \ge 0 \end{cases}$$

We then have, for appropriate limits  $a_j$  and  $b_j$ , depending on j,

$$\varphi_{1}^{j} = \frac{N_{o}}{V_{1}\Delta t} \int_{a_{j}}^{b_{j}} dr \ e^{-\int_{0}^{r} \sigma(r')dr'}$$
$$= \frac{N_{o}}{V_{1}\Delta t} \ \frac{e^{-\int_{0}^{a_{j}} \sigma(r')dr'} - e^{-\int_{0}^{b_{j}} \sigma(r')dr'}}{\sigma(r_{1})}$$

$$\varphi_{i}^{j} = \frac{\sum_{i=1}^{n} \sigma(r') dr' \left[1 - e^{-\sigma(r_{i})(b_{j} - a_{j})}\right]}{V_{i} \Delta t \sigma(r_{i})} \quad . \quad (30)$$

The integration limits  $a_j$  and  $b_j$  shown above are given by the following expressions,

 $a_{j} = \max (r_{1-\frac{1}{2}}, vt)$   $b_{j} = \min (r_{1+\frac{1}{2}}, vt + v\Delta t) ,$ 

provided the intervals  $(vt,vt + v\Delta t)$  and  $(r_{1},r_{2})$  are not disjoint. If these intervals  $i-\frac{1}{2}$   $i+\frac{1}{2}$ are disjoint, then the uncollided flux is zero in the i'th mesh cell during the time step t to t +  $\Delta t$ , so  $\varphi_{1}^{j} = 0$ .

The above expression for  $\varphi_1^j$  was derived for spherical geometry. However, the same expression is valid in slab and cylindrical geometries, with an appropriate cell volume  $V_1$ .

In TIMEX, the average of the uncollided flux at each mesh cell over each time step is evaluated as specified by Eq. (30). This is done separately for each neutron group; the groups are not coupled because there are no scattering terms in the equations for the uncollided flux. These averaged uncollided fluxes are then added to all moments of the collided flux in slab and spherical geometries and to the  $Y_{\ell}^{0}$  moments in cylindrical geometry. This total flux is used in the algorithms that generate the scattering and fission sources.

### F. Boundary Conditions

Five different types of boundary conditions are allowed by the TIMEX code: vacuum, reflective, periodic, white, and albedo. Let  $Y_1(\mu)$  and  $Y_r(\mu)$ be the left and right boundary fluxes, respectively. We will discuss each of these conditions for the right boundary; the left boundary is treated in a similar fashion.

<u>1. Vacuum.</u> The incoming flux is set to zero on the boundary, thus  $\Psi_r(\mu) = 0, \mu < 0.$ 

2. Reflection. The incoming flux is set equal to the outgoing flux in the conjugate direction, that is,  $\Psi_{r}(\mu) = \Psi_{r}(-\mu)$ ,  $\mu < 0$ .

3. Periodic. The incoming flux is set equal to the outgoing flux on the opposite boundary,

therefore,  $\Psi_{\mu}(\mu) = \Psi_{\mu}(\mu), \mu < 0.$ 

<u>4. White</u>. The incoming flux is constant in angle and is chosen so that there is no net flow across the boundary. This is accomplished by setting

$$\Psi_{r}(\mu) = \frac{\int_{0}^{1} \mu \Psi_{r}(\mu) d\mu}{\int_{0}^{1} \mu d\mu} , \mu < 0$$

5. Albedo. The incoming flux is set equal to the albedo times the outgoing flux in the conjugate direction, therefore,

where  $\alpha =$  albedo.

### G. Moving Boundaries

The TIMEX code allows the user to enter new cross sections, sources, coarse-mesh boundaries, velocities, etc., at the beginning of each time zone. Most of these options present no special difficulty for the code. If, however, the user wishes to move the coarse-mesh boundaries with time, then some effort must be expended by the code to interpolate the old fluxes onto the new mesh. There are various ways to accomplish this interpolation; TIMEX uses the simplest method that guarantees conservation of neutrons.

We insist that the outer or right-hand boundary remain fixed during the computation (the left-hand boundary is always fixed at 0.0). This condition is necessary to eliminate the possibility of an extrapolation at the outer boundary. It may be circumvented in some problems by including a large fictitious vacuous cell adjacent to this boundary. With this restriction, the new flux  $v_{1,m}^{new}$  at the i'th mesh cell in the m'th direction is computed from

$$y_{1,m}^{new} = \frac{\frac{1+\frac{1}{2}}{\int_{r^{new}}^{r^{new}} y^{0ld}(r,\mu)dV}}{v_{1}^{new}} .$$
 (31)

The integral appearing in Eq. (31) is a volume integral. The old flux appearing under the integral sign must be construed as a series of step functions in each of the old mesh cells because only cellcentered fluxes are stored by the code.

### **III. PROGRAM DESCRIPTION**

The TIMEX code is written in FORTRAN-IV and is divided structurally into a main program and a number of subroutines with fairly restricted tasks. Because the code is relatively short, it is not necessary to use an overlay structure. Because the subroutines fall naturally into several classes, input and initialization, execution and edit, and service, such an overlay structure would be easy to incorporate into the code.

Variable dimensioning is used exclusively throughout TIMEX. The bulk of the data, such as cross sections, sources, fluxes, and frequencies, resides in extended or large core memory. Only the data pertinent to a single energy group are contained in fast core at a given instant. Therefore, large problems can be run with TIMEX.

### A. Subroutines

A list of TIMEX subroutines with a brief description of the primary functions of each is presented in Table IV. The subroutines are listed in the order of their appearance in TIMEX.

In addition, a number of system routines, listed in Table V, are necessary for the satisfactory execution of the TIMEX code.

### TABLE IV TIMEX SUBROUTINES

TIMEX is the main program. The input routines INPUT1 and INPUT2 are called first. Certain initializations are performed by a call to INITAL; the initial condition is printed by FINAL. Time steps are accomplished by successive calls to OUTER; the subroutine SCALE is called if the extrapolation option is selected. TIMEX reads the time zone cards that specify the number of time steps to be taken and the time step size.

INPUT1 is called by TIMEX. This subroutine reads the control integers and certain floating point constants. Some input checking is performed here.

INPUT2 is called by TIMEX. Calculation of most of the integers in the common block IA is

performed by INPUT2. This subroutine also reads the remaining problem input, often by calls to specialized routines. New values of time-varying parameters are also read by INPUT2 on successive time steps.

- CSPREP is called by INPUT2. Cross sections are read by a call to LAXS, checked, rearranged for an adjoint problem, and stored in Extended Core Storage (ECS).
- READF is called by INPUT2. The initial flux shape is read by this routine and stored in ECS. Various options are permitted here.
- READQ is called by INPUT2. The distributed and boundary sources are read here and stored in ECS.
- SNCON is called by INPUT2. This routine reads or generates the S<sub>N</sub> quadrature set and other special arrays and indices for the treatment of the angular variable.
- INITAL is called by TIMEX. This routine initializes many arrays through calls to several subroutines.

REBOUND is called by INITAL after the first time zone if new coarse-mesh boundaries are read. Its purpose is to interpolate the old flux to the new mesh points in a manner that will conserve particles.

- GEOFUN is called by INITAL. All geometric functions such as mesh spacings, area elements, and cell volumes are generated here.
- INITQ is called by INITAL. The volume and group integrals of the source are performed by this routine, as well as source normalization, if requested. The source is also multiplied here by one-half the mesh spacing for convenience in later calculations.
- INITF is called by INITAL. The fission matrix is computed, transposed for adjoint problems, and stored in ECS. Integrals and normalizations are performed.
- OUTER is called by TIMEX. A single call to OUTER advances the solution by a single time step. The uncollided flux is

computed if that option is specified. A sweep through the energy groups is performed next, with successive calls to SOURCE and TINNER.

- UNCOLL is called by OUTER. This subroutine computes the uncollided flux and stores it in ECS. It is called only if the uncollided flux option is specified.
- SOURCE is called by OUTER. The source to a particular group from all other groups is generated by this routine. The total source for the rebalance acceleration method is also computed.
- TINNER is called by OUTER and is the heart of the code. This routine adds the within group scattering and fission sources to the source generated by SOURCE. With this total source, the flux in a single group is advanced by one time step, or by several partial steps if the time step size depends upon the group. Group rebalance factors are calculated and applied to the flux. Frequencies are computed, and the fluxes are stored in ECS.

FINAL is called by TIMEX and contains all editing and printing logic. Various options are allowed.

- SCALE is called by TIMEX. This routine multiplies the flux by the factor  $e^{\omega\Delta t}$  if the extrapolation option has been selected.
- REBAL is called by TIMEX. This routine solves a tridiagonal algebraic system for the rebalance factors.
- SETEC is called by TIMEX. Boundary conditions are set by this routine.
- MAPPER is called by INPUT2 and draws a diagram of the geometry of the problem.
- DUMPER is called by TIMEX and records on a tape the necessary information for a problem restart at selected time steps. This routine also reads the dump tape when a restart is requested.

LAXS is called by CSPREP and reads cross sections.

- READ is called by several routines. Its function is to read data in the special Los Alamos Scientific Laboratory (LASL) format.
- WRITE is called by several routines and is capable of writing arrays in several formats.

ERROR writes error messages.

- CLEAR clears a block of core.
- ECRITE transfers a block of core into ECS.
- ECREAD transfers a block of ECS into core.
- REDUCE checks core storage requirements and adjusts core size to size of problem.
- PRINTP is called by INPUT2 and prints the control integers.

### TABLE V NECESSARY SYSTEM ROUTINES

Subroutine	Description
SECOND(I)	Returns clock time in seconds.
DATE1(I)	Returns current date in A8 format.
ECWR (CM, EC, LEN, IERR)	Transmits LEN words of fast core beginning with CM into large core beginning with EC. IERR = error parameter.
ECRD (CM, EC, LEN, IERR)	Transmits LEN words of large core beginning with EC into fast core beginning with CM. IERR = error parameter.
Function	Description
SQRT(X)	√x
ATAN(X)	Actan (x)
COS (X)	cos (x)
EXP(X)	e <sup>x</sup>
ALOG(X)	log <sub>e</sub> (x)

### B. Data Storage

Most of the group-dependent data are stored in extended or large core, with space provided in small or fast core only for the data pertinent to a single energy group. All single fixed and floating point parameters are stored in the IA array of blank common. All arrays are stored in the A array of blank common, which immediately follows the IA array. The location of a particular subarray, such as the flux, within block A is specified by a pointer contained in block IA. The computation of all these pointers is performed by the subroutine INPUT2 in such a manner that data are stored compactly in the A block.

A list of these pointers is given in Table VI. This list gives the position in the IA block of each of these pointers and the name and length of the array specified by the pointer. Some of the positions in the IA block are reserved for control integers and floating point constants. These parameters are also listed in Table VI with the meaningless array name blank. A brief description of these parameters is also included in Table VI.

A good many positions in the IA block are not used at present. Sometimes these unused positions have been named. This is because TIMEX was developed from the steady-state code ONETRAN, which had a need for parameters and arrays that are meaningless in a time-dependent context.

## TABLE VI CONTENTS OF BLANK COMMON BLOCK IA

<u>Position</u>	Name	Pointer for Array	Remarks
1	ITH,ITC		Indicator for di-
			rect or adjoint
			problem
2	ISCT		Scattering order
3	ISN		Order of S <sub>N</sub> approx-
			imation
4	IGM		Number of groups
5	IM		Number of coarse-
			mesh intervals
6	IBL		Left-boundary con-
			dition indicator

Position	Name	Pointer for Array	Remarks	Position	Name	Pointer for <u>Array</u>	Remarks
7	IBR		Right-boundary	25	OITM		Not used
			condition indica-	26	IITL		Not used
			tor	27 <sup>·</sup>	IITM		Not used
8	IEVT		Not used	28	IFISS		Indicator for
9	ISTART		Indicator for in-				fission spectrum
			put of initial				or matrix
			condition	29	IEDOPT		Edit option in-
10	IQOPT		Indicator for in-				dicator
			put of sources	30	TTN		Initial time step
11	IGEOM		Geometry indicator	30			number
12	IQUAD		Quadrature indica-	31	IDO		Not used
			tor	37	τρντ		Not used .
13	MT		Number of materi-	52			
			als	33	ICON		Not used
14	MTP		Materials from	34	IMU		Type of quadra-
			tape library				ture cosines
15	MCR		Materials from	35	IPLOT		Flux plot indi-
15			cards				cator
16	WC		Number of mixture	36	IACT		Activity indica-
10 M	115		instructions				tor
			Position of total	37	ITXS		Indicator for
17	IUI		cross section in				time-dependent
			table				cross sections
19	TUC		Position of self-	38	ITQ		Indicator for
10	1115		scatter cross sec-				time-dependent
			tion in table				sources
19	тнм		Cross-section	39	ITB		Indicator for
17			table length				time-dependent
20	TDEN		Indicator for fine-				coarse-mesh
20	IDEN		mesh density fac-				boundaries
			tors	40	ITIDXS		Indicator for
21	TOAN		Order of source				time-dependent
~1	7.4111		anisotropy				cross-section
22	101		Indicator for left-				
~~	IQL		boundary source	41	ITFISS		Indicator for
			Taldaatan Fam				fission spectrum
23	TŐK		right-houndary				- 10
			source	42	ITVEL		Indicator for
			Toddeeten For mo				ume-dependent
24	LACC		Indicator for re-				, CIVCILIED
			tion				

Position	Name	Pointer for <u>Array</u>	Remarks	Position	Name	Pointer for Array	Remarks
43	IIMIX		Indicator for	68	EPSI		Not used
			time-dependent	69	EPSX		Not used
			mixture instruc- tions	70 <sup>.</sup>	EPST		Not used
44	TTDEN		Indicator for	71	POD		Not used
	LEDEN		time-dependent	72	NORM		Normalization
			density factors				factor
45	ITL BDO		Indicator for	73	BHGT		Buckling height
			time-dependent	74	BWTH		Buckling width
1.6	TIMBDO		Tellector for	75	TIMOFF		Dump time
40	TIKBDO		time-dependent	76			Not used
			right albedo	77			Not used
47	ITSTEP		Not used	78			Not used
48	INDTS		Group-dependent	79			Not used
			time step indica-	80	RT IME		Real time
				81	TIME		Computation time
49	1602		first-collision	82	TOUT		Not used
			source	83	IDUMP		Not used
50			Not used	84	EPSR		Not used
51			Not used	85			Not used
52			Not used	86			Not used
53			Not used	87			Not used
54			Not used	88			Not used
55			Not used	89			Not used
56			Not used	90			Not used
57			Not used	91			Not used
58			Not used	92			Not used
59			Not used	93			Not used
60			Not used	94			Not used
61	EV		Not used	95			Not used
62	EVM		Not used	96	TACC		Not used
63	PV		Not used	97	IGCDMP		Not used
64	XLAL		Not used	98	TIN		Not used
65	XLAH		Not used	99	TSLDMP		Not used
66	XLAX		Not used	100	TIMBDP		Not used
67	EPSO		Not used	101	MIN		MCR+MTP

•

•

•

•

۰.

15

•

Position	Name	Pointer for Array	Remarks	Position	Name	Pointer for Array	Remarks
102	IUP		IHS-IHT-1	131	LIHR	IHR (JM)	Number of fine-
103	IHF		IHT-1				mesh intervals
104	IHA		IHT-2	,			per coarse-mesh
105	MM		Total number of di-				zone
100			rections	132	LW	WGT (MM)	Quadrature weights
106	NM		Total number of flux components	133	LU	U (MM)	Direction cosines
107	NMQ		Number of source	134	LWM	WMU (MM)	Product WGT*UB
			components	135	LBP	BP (MM)	Curvature coeffi-
108	M2		MM/2				cient $B(M+\frac{1}{2})$
109	NN		ISN/2	136	LBM	BM (MM)	Curvature coeffi- cient $B(M-\frac{1}{2})$
110	IP		IM+1	137	LDM	BS (MM)	2 Sum BP+BM
111	IGP		IGM+1	120	100	55 (11)	
112	IHMT		MT*IHM	130	LSE	SE(MM)	NOT USED
113	ISCP		ISCT+1	139	LSC	SC (MM)	Not used
114	M2P		Not used	140	LUB	UB(ISN)	Full range quadra- ture cosines
115	ITMM		IT*MM	141	LWB	WB(ISN)	Level weights
116	ITP		IT+1	142	LCM	MC (MM)	Not used
117	ITPM		ITP*MM	143	LME	ME (MM)	Not used
118	IMGP		IM*IGM	144	TPN		Sabordeel berroe
119	IT		Number of fine-mesh	144			ic function
			intervals	145	LLI	LI(MM)	Level indices
120	IHNN		IHT-3	146	 I.FT		Not used
121	IPGP		IP*IGM	147			Not used
122	IFISP		Zone fission spec-	147			Not used
			trum indicator	148			Not used
123	LFLM		LQA-1	149			Not used
124	EVR		Not used	150	LC	C(IHM,MT)	Cross-section array
125	KM	-	Not used	151			Not used
126	IAFT		3*ITMM+ITPM	152	LCT	CT(IT)	Total cross sec-
127	KEND		Length of ECS needed		201	02(22)	tion
128	LAST		Length of block A of blank common	153	LCS	CS(IT)	Scattering cross section
129			Not used	154	LCA	CA(IT)	Absorption cross
130			Not used				section
				155	LCF	CF(IT)	vo <sub>f</sub> cross section

•

.

Position	Name	Pointer for Array	Remarks	Position	Name_	Pointer for Array	Remarks
156	LDC	IDC(IP)	Cross-section	182			Not used
			identifiers	183			Not used
157	lmn	MIXNUM (MS)	Mixture numbers	184			Not used
158	LMC	MIXCOM (MS)	Mixture commands	185			Not used
159	LMD	MIXDEN(MS)	Mixture densities	186			Not used
160	LMT	MTT(2*MTP)	Identifiers for	187			Not used
			materials from tape library	188	LRAD	RAD(IP)	Coarse-mesh radii
161	LDEN	DEN(IT)	Density factors	189	LIDR	IDR(IT)	Coarse-mesh
162	LNMA	NMAC(IACT)	Activity material numbers				zone identi- fiers
163	LNPA	NPAC(IACT)	Activity cross-	190	LH	H(IM)	Mesh spacings
164	LACT	ACT(IACT,IT)	Activities	191	LAI	AI(ITP)	Fine-mesh areas
165			Not used	192	LV	V(ITP)	Fine-mesh vol-
166	LÖ	Q(NM,IT)	Distributed source				umes
167	LQR	QR (M2)	Right-boundary	193	LAP	AP(ITP)	AI(I+1)/AS(I)
			source	194	LAM	AM(ITP)	AI(I)/AS(I)
168	LQL	QL (M2)	Left-boundary	195	LAS	AS(ITP)	AI(I+1)/AI(I)
169	1 61	ET IN (NM TT)		196	LAD	AD(ITP)	AP-AM
170		HE(IT)	Flux components	197	LR	R(ITP)	Fine-mesh radii
170	LFLB	FLUXB(IT)	Scalar flux	198	LRAV	RAV(ITP)	Fine-mesh aver- age radii
172	LFLT	FLT	Not used	199	LRM		Not used
173	LCUR	CUR	Not used	200	LRDA	RADA(ITP)	Fine-mesh radii
174	LIN	FIN	Not used				from previous
175	LBL	BL(M2)	Left-boundary flux				time zone
176	LBR	BR (M2)	Right-boundary flux	201	LDEL	DEL(IP)	Distance be- tween coarse-
177	LAFE	AFE(MM, ITP)	Angular flux on				mesh boundaries
			cell boundary	202	LIED		Not used
178	LAFC	AFC(MM,IT)	Angular flux on µ boundaries	203	<u>l</u> dh	DH(ITP)	0.5*DEN*H Not used
179	LQA	QA(MM,IT)	Angular source	205	LUFS	UFS	Uncollided flux
180	LTA	TA (MM, IT)	Angular flux at				spectrum
181	I.P	۲ <b>۳</b> ۱)	cell centers	206	LIUF	IUF (IGM)	Mesh position
101	μr	* (**)	cross section				flux

Position	Name	Pointer for <u>Array</u>	Remarks	Position	Name	Pointer for <u>Array</u>	Remarks
207	LIGT	IGTSF(IGM)	Number of time	237	LSGG		Not used
			steps per group	238	LTD		Not used
208	LQG	QG(IGP)	Total inhomogene-	239			Not used
200	I DO	PO(ICB)	Total fiction	240			Not used
209	LFG	rG(1Gr)	sources	241			Not used
210	LSIN	SIN(IGP)	Inscattering	242			Not used
211	LSS	SS(IGP)	Self-scattering	243	LOMG	FREQ(IT)	Frequencies
212	LSOU	SOUT(IGP)	Outscattering	244	LENC		ECS length of
213	LRL	RL(IGP)	Right leakage				artay
214	LNL	NL(IGP)	Net leakage	245	LENQ		ECS length of
215	LABG	ABG(IGP)	Absorption				source array
216	LBAL	BAL(IGP)	Balance	246	LENF		ECS length of
217	LCHI	CHI (IGM)	Fission spectrum				flux arrays
21.0	1.0.01	VET (TOP)	(also CHI(IM,IGM))	247	LENS		ECS length of source to
218	LVEL	VEL(IGP)	Velocities				group
219	LAF	T PDO(ICP)	Not used	248	LNAF		ECS length of
220		PBDO(ICP)	Right albedo				angular flux
222	LKB	KBDO(IGF)	Not used	240	1 1020		array
222			Not used	249	LNFS		fission spec-
22J			Not used				trum array
224			Not used	250	LENP		Not used
225			Not used	251	LNFG		Not used
220	TE	8(17)	Not used	252	LNSG		Not used
227	LF	r(11) FD(TTP)	Right flows	253	LNUF		ECS length of
220		FR(117)	Left flows				uncollided flux
229	LELL	ГЦ(117) Ав(тт)		254			array Not used
230	LOO		Rebalance source	234	KOM		FCS position
232	LOOG	QQ(11)	Not used	233	Kom		of frequency
 	LCD		Not used				array
226		11A (TT)		256	КС		ECS position of
234	LIIX	RA(11)	used in REBAL				cross-section array
235	LGA	GA(IT)	Temporary array	257	KQ		ECS position of
			used in REBAL				source array
236	LFGG		Not used	258	KF		ECS position of
							flux array

•

•

•

•

18

~

.

Position	Name	Pointer for <u>Array</u>	Remarks	Position	Name	Pointer for Array	Remarks
259	KS		ECS position of	287	IUPTOT		Not used
			source to group	288	JCONV		Not used
			allay	289	TS		Not used
260	KAF		ECS position of angular flux ar-	290	IITNO		Not used
			ray	291	G		Group index
261	KFS		ECS position of	292	TF		Not used
			fission spectrum	293	AFA ,AF		Not used
262	КР		Not used	294	NGO		Not used
263	KFG		Not used	295	NGOTO		Not used
264	KSG		Not used	296	ICONV		Not used
265	KF2		ECS position of	297			Not used
			scalar flux from	298	DELTAT		Time step size
			step	299	KSTEP		Time sten .
266					NO I DI		counter
200	KUP		uncollided flux	300	IFREO		Frequency in-
267			Not used				dicator
268			Not used				
269	ALR		Not used				
270	ALL		Not used	C. Proble	em Restart		
271	SUMMUL		Not used	If th	he problem	being run requir	es a consider-
272	SUMMUR		Not used	able amoundump core	nt of compu occasional	iter time, it is Ilv onto a tape i	advisable to .n such a wav
273	OITNO		Not used	that the	problem car	be restarted at	selected time
274	IITOT		Not used	steps. T	his option	is incorporated	in the TIMEX
275	E1		Not used	code. In	each time	zone the user ca	red The prob-
276	E2		Not used	lem can th	hen be rest	arted at any of	the time steps
277	E3		Not used	at which a	a dump was	taken. This is	accomplished
278	E4		Not used	by setting	g ISTART =	5 and ITN equal	to the selected
279	EVP		Not used	tape dumps	s will be v	written in succes	sion on the
280	EVPP		Not used	same tape	from which	the restart dat	a were taken,
281	ALA		Not used	starting : the select	immediately ted restart	y following the r t time step numbe	estart data at er. Old data
282	ALAR		Not used	following	this time	step will be obl	iterated by the
283	XLAP		Not used	new data.	If it fel	lt that the resta	rt tape is ap-
284	XLAPP		Not used	proaching	capacity,	then setting IST	CART = -5 will
285	EVS		Not used	taken so	s cape to f that all of	the old data is	obliterated.
205	10NT		Not used	Seve	ral paramet	ters may be chang	ged at a restart.
200	TCMI.		Not used	These para	ameters are	e ISTART, LACC, I	EDOPT, ITN,

IPLOT, and ITXS through ITRBDO. All other parameters must be left unchanged. TIMEX reads only cards 1 through 7 and card 31 (see Sec. V), if the restart option is selected. All other input data are obtained from the dump tape and must not be entered on cards.

Each restart dump results in the writing of IGM + 2 records on tape. The first record contains the parameters KSTEP, IGM, NM, IT, L, and LENIA, where L = LAST + LENIA. The parameter LENIA is the length of the IA block (currently 300 words) and L is the total length of the IA and A blocks. The second record contains all of fast core, and the succeeding IGM records contain all the extended core data.

### D. Input/Output Files

The input/output (I/O) file designators are stored in a common block labeled UNITS. The assignment of file designators is given in Table VII.

### IV. DETAILED INPUT SPECIFICATION

Most of the input data, with the exception of cross sections and control integers, are read in a special format that provides for automatic repetition and interpolation. This format is referred to as the LASL format in the remainder of this report. When the LASL format is specified for a block of integer or floating-point data, then these data are entered, six numbers to a card, in the formats [6(I1,I2,I9)] or [6(I1,I2,E9.4)], respectively. Two integers must proceed each data word in this

### TABLE VII ASSIGNMENT OF I/O FILE DESIGNATORS

File Name	Logical Unit	Remarks	3
NINP	10	System input unit	
NOUT	9	System output unit	
NFILM	12	System film unit	4
NLAXS	6	Cross-section library	
NAFLX	8	Angular flux tape	5
NDUMP1	7	Restart dump tape	
NDUMP 2	5	Not used	9

format. The first integer specifies the desired option according to Table VIII; the second integer controls the execution of the particular option selected by the first integer.

Five examples of the use of the special LASL formats are given in Table IX. These examples result in the input of the following blocks of data:

- (1) A block of 47 zeros is read.
- (2) A block of 470 zeros is read.
- (3) Four interpolants are inserted between 0.0 and 5.0, giving a block of six numbers: 0.0, 1.0, 2.0, 3.0, 4.0, and 5.0.
- (4) Four interpolants are inserted between
  0.0 and 5.0, two between 5.0 and 7.0, and
  7.0 is repeated 10 times. A total of 18 numbers are entered in the data block.
- (5) The data block consists of the three integers: 0, 4, and 7.

### TABLE VIII OPTIONS FOR LASL FORMATS

Value of Il	Option
0 or blank	Single data word entered in block.
1	Repeat following data word number of times indicated in I2 field.
2	Place number of linear interpolants indicated in I2 field between this data word and next data word. Total entries in block equals number in I2 field plus 2.
3	Terminates reading of data block. Every block must be terminated with a 3 in the Il position.
4	Fill remainder of block with following data word. Remember to terminate with a 3.
5	Repeat following data word 10 times the number in the I2 field.
9	Skip to next data card.

TABLE IX

Example	Card Image
	1 1 1 1 1 1 1 1 1 1 2 2 2 2 2 2 2 2 2 2
1	1470.03
2	5470.03
3	2 4 0.0 5.0 3
4	2 4 0.0 2 2 5.0 110 7.0 3
5	0 4 9
5	7 3
	1 1 1 1 1 1 1 1 1 1 2 2 2 2 2 2 2 2 2 2

EXAMPLES OF THE USE OF LASL FORMAT	EXAMPLES	OF	THE	USE	OF	LASL	FORMAT
------------------------------------	----------	----	-----	-----	----	------	--------

The input data are listed in the order in which they must be read in to the code. These data are divided into three categories, title information, control parameters, and input arrays. The title information and control parameters must be entered in full for all problems, including restart problems, but many of the input arrays are optional. None of the input arrays are entered for a restart problem because they are obtained from the dump tape.

### A. Title Information

The first card in the problem deck must contain an integer in I6 format, which specifies the number of title cards to be read. The appropriate number of title cards must then be entered. These cards should contain descriptive information about the problem and are read in a 12A6 format.

### B. Control Parameters

A total of five cards must be entered. The first four cards contain integer data in a 1216 format and the next card contains floating-point data in a 6E12.6 format. These data are adequately described in Sec. V.

### C. Input Arrays

<u>1. Fine Mesh.</u> This is the mesh on which the difference approximations are taken. Each finemesh interval is contained in a coarse-mesh zone. Each coarse-mesh zone may contain one or more finemesh intervals. All material properties are assumed constant within a single-coarse mesh zone with the exception of the material density, which may depend upon the fine mesh (see paragraph 12 below). The fine mesh is specified by giving the number of finemesh intervals in each coarse-mesh zone.

2. Quadrature Weights and Points. The  $P_N$ (Gaussian) quadrature sets are built into the code for N = 2, 4, 6, 8, 12, 16, 20, 24, 32, and 48. The DP<sub>N</sub> quadrature is also available for N = 4, 8, 12, 16, 24, 32, 40, 48, 64, and 96. These quadratures are obtained by setting IQUAD = 1 or 2, respectively. If IQUAD = 3, then both weights and cosines must be read in to the code. An array of MM weights and an array of MM cosines are required where MM = ISN in slab or spherical geometry, and MM = ISN\*(ISN+2)/4 in cylindrical geometry. The weights are read in first.

3. Library Cross Sections. If cross-section data are to be obtained from a library, an array containing the identification numbers of the desired library materials must be entered. The first and subsequent entries in this array will be assigned the TIMEX identification numbers 1, 2, ..., MTP for the purpose of assigning these materials to a particular coarse-mesh zone (see paragraph 8).

4. Cross Sections. The standard LASL crosssection format is used by the TIMEX code. In this format a single block of IHM X IGM numbers is required for each nuclide (assuming scattering is isotropic). IHM and IGM are input parameters and are the "table length" and the number of energy groups, respectively. We consider this single block to consist of a set of IGM subblocks or "tables" of length IHM. Each table contains the cross sections indicated in Table X. The positions of the total and self-scatter cross sections within the table are given by the input parameters IHT and IHS, respectively.

In this format, downscattering through M groups and upscattering through N groups is allowed (recall the group g+1 is of lower energy than group g). In the notation of Table X,  $\sigma_a$  = absorption cross section,  $v\sigma_f$  = product of the mean number of neutrons per fission times the fission cross section,

 $\sigma_t = \text{total cross section, and } \sigma_{g' \rightarrow g} = \text{cross section}$ for scattering from group g' to g, Additional cross sections may be entered preceding IHT-2 in the table

### TABLE X

### STRUCTURE OF CROSS-SECTION BLOCK

Position	Cross Section
	•
•	•
	•
IHT-2	σa
IHT-1	νσ <sub>f</sub>
IHT	σ <sub>t</sub>
IHT+1	σ <sub>g+№</sub> g
•	•
	•
IHS-2	σ <sub>g+2→g</sub>
IHS-1	σ <sub>g+1→g</sub>
IHS	σ g→g
IHS+1	σ <sub>g−1→g</sub>
IHS+2	σ g−2→g
•	•
•	
IHS+M	σ s,g-M→g

for editing purposes (activation, etc.), although such cross sections are not used in the calculation. If no upscattering is to be allowed, IHS = IHT+1. Also, all cross-section blocks, including those from the library, must be in the same format with the same values of IHM, IHT, and IHS.

Each cross-section block must be preceded by a title card, which is read in the format (12A6). After the title card a single block of cross sections is read in a (6E12.5 format). The entries must be ordered within subblocks as indicated in Table X, and these subblocks must be ordered according to group index, with the cross sections for group 1 first.

Each nuclide read from cards is assigned a TIMEX identification number in the order of input, starting with MTP+1.

If the computation of an anisotropic scattering source is desired, additional cross sections are necessary. These cross sections are the Legendre components of the expansion of the scattering kernel (see Eq. (5)),  $\sigma_{\mu}^{S}(r,g' \rightarrow g)$ . These anisotropic scattering cross sections must be entered as additional cross-section blocks, one for each term in the expansion, immediately following the primary cross sections for that nuclide. These additional blocks are entered in the same manner as the primary cross sections, each block being preceded by a title card. The entries in these blocks corresponding to  $\sigma_{a}$ ,  $v\sigma_{f}$ , and  $\sigma_{t}$  are meaningless and are not used in the calculations. These anisotropic blocks are treated by the code in exactly the same manner as a . nuclide and are assigned identification numbers in sequence. If desired, these blocks can be mixed (see paragraph 11).

In an adjoint calculation, cross sections are entered in exactly the same way as for a direct calculation. The code then performs the necessary transpositions to form the adjoint operators.

5. Initial Flux. In a time-dependent problem the complete angular flux at the initial time is needed to begin the calculation. Because this is an enormous array, various options that simplify its input are provided in the TIMEX code. These options are selected by the ISTART parameter, which may assume the values given in Table XI.

If the right (or outer) boundary is other than vacuum, the angular flux on the boundary is also

### TABLE XI

### ISTART OPTIONS

ISTART	Entries	IQOP
0	Initial flux set to zero. No entries re- quired.	0
1	First-collision source option. Enter energy shape for uncollided flux, IGM num- bers.	1
2	Isotropic initial flux. If IBR = 0 enter IGM blocks of IT fluxes. Otherwise, enter a block of IT fluxes and a block of MM/2 right-boundary fluxes for each energy group.	2
3	Complete angular flux. If IBR = 0 enter IGM blocks of IT*MM fluxes (all angular fluxes at a space point must be grouped). Otherwise, enter a block of IT*MM fluxes and MM/2 right-boundary fluxes for each energy group.	3
4	Obtain angular flux from tape. No entries	
	redutter.	- 4

5 Restart problem; angular flux obtained from restart tape at selected time step. No entries required.

needed to begin the calculation. If ISTART = 0, these boundary fluxes are set to zero. Only a vacuum right boundary is allowed if ISTART = 1. Otherwise, these boundary fluxes must be read in as specified in Table XI.

<u>6.</u> Sources. Both boundary and distributed sources can be read in to the code. Distributed sources may be isotropic or anisotropic, in which case NMQ spherical harmonic moments of the source are entered. In slab or spherical geometry NMQ = IQAN+1, but in cylindrical geometry NMQ =  $(IQAN+2)^2/4$ . Various input options are allowed for the sources; these options are discussed in Table XII.

<u>7. Coarse-Mesh Radii</u>. The radii (or x-coordinates) of the coarse mesh must be entered. The left-hand radius must be zero in all cases, including slab geometry. This zero must be entered so

### TABLE XII

### SOURCE INPUT OPTIONS

IQOPT	Entries
ο ΄	All sources set to zero. No entries re- quired.
1	Energy spectrum on all sources. Enter IGM distributed sources. If $IQL \neq 0$ enter IGM left-boundary sources and if $IQR \neq 0$ enter IGM right-boundary sources.
2	Complete distributed source, spectrum on boundary sources. Enter NMQ blocks of IT distributed sources for each group. If $IQL \neq 0$ , enter IGM left-boundary sources after group one distributed sources. If $IQR \neq 0$ , enter IGM right-boundary sources following left-boundary sources.
3	Zero distributed source, spectrum on bound- ary sources. If IQL $\neq$ 0 enter IGM left- boundary sources, and if IQR $\neq$ 0 enter IGM right-boundary sources.
4	Energy spectrum on distributed source, com- plete boundary sources. Enter IGM distri- buted sources. For each group enter MM/2 left-boundary sources if IQL $\neq$ 0, and MM/2 right-boundary sources if IQR $\neq$ 0.
5	Complete sources of all types. For each group enter NMQ*IT distributed sources, MM/2 left-boundary sources if IQL $\neq$ 0, and MM/2 right-boundary sources if IQR $\neq$ 0.
that a : <u>8.</u>	total of IM+1 radii are required. Cross-section Identification. An integer
must be	assigned to each coarse-mesh interval.
These in	ntegers must be valid cross-section identi-
fiers s	pecifying the particular material contained
within a	a coarse-mesh zone. If the computation of
an anise	otropic scattering source is desired within a
coarse-	mesh zone, then the material ID number for
that zon	ne must be tagged with a minus sign, other-
wise is	otropic scattering is assumed. A total of
IM cross	s-section identifiers must be entered.

<u>9. Fission Spectrum</u>. Either a fission spectrum or a fission matrix can be specified; either of these may depend on the coarse-mesh zone. Selection of these options is accomplished by means of the IFISS parameter, which can be assigned the values given in Table XIII.

<u>10. Velocities</u>. A total of IGM group velocities must be entered.

11. Mixture Tables. Cross-section tables read from cards or a tape library may be manipulated or mixed to form new materials or alter old ones. This is accomplished by entering a set of mixture instructions. The number of such instructions is given by the input parameter MS. A mixture instruction consists of a single entry in each of the integer arrays MIXNUM and MIXCOM and in the real array MIXDEN. The mixture instructions are executed sequentially. The execution of a single mixture instruction results in the addition to cross-section block MIXNUM of MIXDEN times the contents of crosssection block MIXCOM. If MIXCOM = 0, then the cross-section block MIXNUM is multiplied by MIXDEN. Let us consider a few simple examples. Suppose five materials have been read in and MS = 4. The mixture instructions in Table XIV will produce the following results. First, the cross sections of material 1 are all multiplied by 0.5. Next, crosssection block six is cleared. Then material 6 is formed by adding 0.01 times the contents of block 2 to 10.1 times the contents of block 4. It is important when forming a new material, like 6 above, to clear the block initially, otherwise, garbage cross sections may result.

The three arrays, each consisting of a block of MS entries, are entered in the order: MIXNUM, MIXCOM, and MIXDEN.

### TABLE XIII IFISS OPTIONS

FISS	Entries
1	Fission spectrum. Enter IGM numbers.
2	Zone-dependent fission spectrum. Enter IM*IGM numbers.
3	Fission matrix. Enter IGM blocks of IGM numbers.
4	Zone fission matrix. Enter IGM blocks of IM*IGM numbers.

### TABLE XIV SAMPLE MIXTURE INSTRUCTIONS

MIXNUM	MIXCOM	MIXDEN
1 ·	0	0.5
6	0	0.0
6	2	0.01
6	4	10.1

<u>12.</u> <u>Density Factors</u>. Although only a single material is permitted within each coarse-mesh zone, the densities of that material can vary on the fine mesh. This is accomplished by the input of an array of IT densities. This array is read only if IDEN  $\neq$  0, otherwise the densities are set to 1.0. The cross sections at any mesh interval are then found by multiplying the cross sections for the appropriate coarse-mesh zone by the density factor for this interval.

13. Albedos. If IBL = 4, a total of IGM left albedos must be entered. If IBR = 4, a total of IGM right albedos must be entered.

<u>14. Activities.</u> If IACT  $\neq$  0, the TIMEX code will calculate activities for selected cross sections. An activity A, depending on position x, is defined as

 $A(x) = \sum_{g} \sigma_{g} \phi_{g}(x)$ ,

where  $\sigma_g$  is any desired cross section in the g'th energy group. The selection of the cross sections for which activities are desired is accomplished by entering two arrays, NMAC and NPAC, each of which contains IACT entries. The array NMAC specifies the table in which the cross section is located; NPAC specifies the position of the cross section within the table.

15. Time Step Control. TIMEX assumes that the time axis has been divided into a series of time zones. Each time zone is further divided into one or more time steps of equal size. Within a time zone all physical parameters are assumed to be constant. These time zones are delineated by entering a set of cards, one for each time zone, that give vital information such as the number of time steps in the zone and the time step size. As many of these cards as desired may be entered. These cards are read in the format 616, E12.5 and contain the information given in Table XV.

If INDTS = 1, then group dependent time step sizes are indicated. The size of the time step within a particular group is specified by entering an array of time step scale factors, which are integers. The time step in a group is then given by the time step size entered on the time zone control card divided by the time step scale factor for that group. The scale factor array (IGM entries) should be entered only if INDTS = 1 and must immediately follow the zone control card.

### TABLE XV TIME ZONE CONTROL CARD

Input Parameter	Remarks
NTS	Number of time steps in this zone. If NTS = -1, the input arrays indicated by nonzero parameters ITXS through ITRBDO must be entered. Set NTS = 0 to ter- minate problem.
NSPP	Number of steps per printout.
NSPD	Number of steps per restart dump.
IFREQ	Set IFREQ = 1 if the exponential extrap- olation acceleration method is to be used over this zone. Otherwise set IFREQ = 0.
INDTS	Set INDTS = 1 for group dependent time step sizes; otherwise set INDTS. If INDTS = 1, enter time step scale fac- tors on following card.
IEDOPT	Output edit options 0/1/2/3/4/5, Nothing/Activities/Activities + Flux Components/Activities + Flux + Frequen- cies/Activities + Flux + Angular Flux/

Activities + Flux + Angular Flux + Fre-

V. QUICK REFERENCE INPUT INSTRUCTIONS

	•	
CARD	TYPE 1	FORMAT (16)
	Number of	title cards
CARD	TYPE 2	FORMAT (12A6) Repeat ITC times
	Title	
CARD	TYPE 3	FORMAT (1216)
	ITH	0/1 Direct/Adjoint
	ISCT	O/N Isotropic/N'th Order Anisotropic
	ISN	SN Order
	IGM	Number of Groups
	IM	Number of Coarse-Mesh Intervals
	IBL	Left-right Boundary Condition-
		0/1/2/3/4
	IBR	Vacuum/Reflective/Periodic/White/
		Albedo
	ISTART	0 Through 5 Starting Options
	IQOPT	0 Through 5 Source Input Options
	IGEOM	1/2/3 Plane/Cylinder/Sphere
	IQUAD	1-PN W and MU, 2-DPN W and MU,
		3-Read W and MU
	MT	Total Number of Materials
CARD	TYPE 4	FORMAT (1216)
	MTP	Number of Materials from Library
	MCR	Number of Materials from Cards
	MS	Number of Mixture Instructions
	IHT	Row of Total Cross Section
	IHS	Row of Self Scatter Cross Section
	IHM	Last Row of Cross-Section Table
	IDEN	0/1 No/Yes Space-Dependent Material
		Density
	IQAN	O/N Isotropic/N'th Order Anisotropic
		Source
	IQL	0/1 No/Yes Left-Boundary Source
	IQR	0/1 No/Yes Right-Boundary Source
	LACC	O-Nothing, 1-Coarse-Mesh Rebalance
	IFISS	1/2/3/4 Fission Fractions/Zone
		Fission Fractions/Fission Matrix/
		Zone Fission Matrix
CARD	TYPE 5	FORMAT (1216)
	I EDOPT	Output Edit Option
	ITN	Restart Time Step Number
	IPLOT	<b>O/l No/Yes Plot Final Flux</b>
	LACT	Number of Activities

DELTAT Step size in this time zone.

quencies.

### CARD TYPE 6 FORMAT (1216)

One or more of the following arrays may be

loaded at each time zone.

	ITXS	0,NO/1, Cross Sections
	ITQ	0,NO/1, Sources
	ITB	0,NO/1, Coarse-Mesh Boundaries
	ITIDXS	0,NO/1, Cross-Section Identification
	ITFISS	0,NO/1, Fission Spectrum
	ITVEL	0,NO/1, Velocities
	ITMLX	0,NO/1, Mixture Instructions
	ITDEN	0,NO/1, Density Function
	ITLBDO	0,NO/1, Left Albedo Factors
	ITRBDO	0,NO/1, Right Albedo Factors
CARD	TYPE 7	FORMAT (6E12.6)
	NORM	Normalization Amplitude
	BHGT	Buckling Height in CM
	BWTH	Buckling Width in CM
	TIMOFF	Time (Seconds) After Which Dump
		Taken
CARD	TYPE 8	FORMAT (LASL)

- Number of fine-mesh intervals in each coarsemesh zone, IM entries.
- <u>CARD TYPE 9</u> FORMAT (LASL) Skip if IQUAD = 1, 2 Quadrature weights, MM entries

If IGEOM = 1, 3 MM = ISN

If $IGEOM = 2$	NN	-	$\frac{1SN*(1SN+2)}{4}$
----------------	----	---	-------------------------

CARD TYPE 10 FORMAT (LASL) Skip if IQUAD = 1, 2

Quadrature cosines, MM entries.

CARD TYPE 11 FORMAT (LASL) Skip if MTP = 0 Library cross section ID, MTP entries.

Repeat card types 12 and 14 MCRC times.

CARD TYPE 12 FORMAT (12A6)

Cross-section title card

CARD TYPE 13 FORMAT (6E12.5) Repeat as needed All cross sections for a single material, IGM\*IHM entries.

### ISTART OPTIONS

- 0 Zero initial flux; skip cards 14 and 15.
- 1 Energy shape for uncollided flux; enter card 14, skip card 15.
- 2 Isotropic initial flux; if IBR = 0 enter card 14 IGM times, if IBR > 0 enter cards 14 and 15 IGM times.
- 3 Complete angular flux; if IBR = 0 enter card 14 IGM times, if IBR > 0 enter

cards 14 and 15 IGM times.

4 Angular flux obtained from tape; no entries required.

5 Restart problem; no entries required.

CARD TYPE 14 FORMAT (LASL) Repeat as needed Initial flux. Enter numbers according to

following table.

ISTART	Entries
0	0
1	IGM
2	IT
3	IT*MM
4	0
5	0

CARD	TYPE	15	FORMAT (LASL)	Skip	if	IBR =	0

Boundary flux. Enter numbers according to following table.

ISTART	Entries
0	0
1	0
2	MM/2
3	MM/2
4	0
5	0

### IQOPT OPTIONS

- 0 Zero sources. Skip cards 16, 17, and 18.
- Energy spectrum on all sources.
- 2 Complete distributed source, spectrum on boundary sources. Enter cards 16, 17, and 18, repeat cards 16 IGM-1 times.
- 3 Zero distributed source, spectrum on boundary sources. Skip card type 16, enter card types 17 and 18.
- 4 Energy spectrum on distributed source, complete boundary sources. Enter cards 16, 17, and 18, repeat card types 17 and 18 IGM-1 times.
- Complete sources of all types. Enter card types 16, 17, and 18 IGM times.

CARD TYPE 16 FORMAT (LASL) Repeat as needed

Distributed source. Enter numbers according to following table.

IQOPT	Entries
0	0
1	IGM
2	NMQ* blocks of IT
3	0
4	IGM
5	NMQ <sup>a</sup> blocks of IT
a NMQ =	$\begin{bmatrix} IQAN+1, IGEOM=1, 3\\ (IQAN+2)^2\\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ &$

CARD TYPE 17 FORMAT (LASL) Skip if IQL = 0

Left-boundary source. Enter numbers according to following table.

IQOPT	Entries
0	0
1	IGM
2	IGM
3	MM/2
4	MM/2
5	MM/2

CARD	TYPE	18	FORMAT	(LASL)	Ski	<b>i</b> f	IQI	<b>λ</b> = 0
	Right	t-bound	lary sou	irce.	Enter	as	for	left-
bound	lary s	source	above.					

<u>CARD TYPE 19</u> <u>FORMAT (LASL)</u> Coarse-mesh radii, IM+1 entries.

CARD TYPE 20 FORMAT (LASL) Cross section ID, IM entries.

CARD TYPE 21 FORMAT (LASL)

Fission spectrum or matrix. Entries according to table below.

IFISS	Entries
1	IGM
2	IM*IGM
3	IGM blocks of IGM
4	IGM blocks of IM*IGM

	Mixture	commands, MS entr	ies.			
CARD	TYPE 24	FORMAT (LASL)	Skip	if	MS ≃	0
	Mixture	numbers, MS entri	es.			
CARD	TYPE 23	FORMAT (LASL)	Skip	1f	MS =	0
	Velocit	les, IGM entries.				
CARD	TYPE 22	FORMAT (LASL)	•			

CARD TYPE 25	FORMAT	(LASL)	Skip	1f	MS	=	0
Mixture	densities,	MS ent	ries.				

- <u>CARD TYPE 26</u> FORMAT (LASL) Skip if IDEN = 0 Density factors, IT entries.
- <u>CARD TYPE 27</u> FORMAT (LASL) Skip if IBL < 4 Left albedos, IGM entries.
- <u>CARD TYPE 28</u> <u>FORMAT (LASL</u>) Skip if IBR < 4 Right albedos, IGM entries.
- <u>CARD TYPE 29</u> FORMAT (LASL) Skip if LACT = 0 Activity material numbers, LACT entries.
- <u>CARD TYPE 30</u> FORMAT (LASL) Skip if IACT = 0 Activity cross-section positions, IACT entries.

Repeat card types 31 and 32 for each time zone.

CARD	TYPE 31	FORMAT (616, E12.6)
	NTS	Number of time steps. If NTS = $-1$
		input arrays specified in card type
		6. Set NTS = 0 to terminate prob-
		lem.
	NSPP	Number of time steps per printout.
	NSPD	Number of time steps per restart
		dump.
	IFREQ	0,NO/1, frequency extrapolation.
	INDTS	0,NO/1, group-dependent time step
		sizes.
	IEDOPT	Edit options 0/1/2/3/4/5, Nothing/
		Activities/Activities + Flux/
		Activities + Flux + Frequencies/
		Activities + Flux + Angular Flux/
		Activities + Flux + Angular Flux
		+ Frequencies.
	DELTAT	Time step size.

<u>CARD TYPE 32</u> FORMAT (LASL) Skip if INDTS = 0 Time step scale factors, IGM entries.

### VI. SAMPLE PROBLEM

The following sample problem illustrates most of the input options, features, and output formats of the TIMEX code. The problem is an instantaneous point burst of neutrons at the center of a sphere. The uncollided flux option is exercised. There are two neutron groups and three coarse-mesh intervals, each containing 10 fine-mesh intervals. An  $S_8$  approximation is used. Three cross-section sets are used in the calculation. Two are read from cards and the third is mixed. Space-dependent material densities are used; these densities are allowed to vary with time during the course of the calculation. The left boundary is reflecting (necessary at the center of a sphere) and the right boundary is vacuum. Zone dependent fission matrices are entered.

The input cards necessary for this sample problem are listed in Table XVI. Card 1 indicates that two title cards are to be read, which follow as cards 2 and 3. Cards 4 through 6 contain the control integers. Card 7 indicates that new material densities may be read in at each time zone, if desired. Card 8 contains certain floating point control parameters. Card 9 is the first card in LASL format and results in the input of an array of three integers, each of which equals 10. These integers specify the number of fine-mesh intervals in each of the three coarse-mesh zones. Cross sections are entered on cards 10 through 15. Card 16 contains the uncollided flux spectrum. Card 17 results in the input of four numbers, 0.0, 10.0, 20.0, and 30.0, which are the coarse-mesh radii. Three integers specifying the material contained in each coarse-mesh zone are entered on card 18.

### TABLE XVI

### INPUT CARDS FOR SAMPLE PROBLEM

### 2 CARD 1 SAMPLE PROBLEM CARD 2 INSTANTANEOUS POINT BURST IN SPHERE CARD 3 0 0 8 2 3 0 0 1 1 3 1 3 CARD 4 n 2 5 3 3 6 1 0 0 0 С 4 CARD 5 2 0 0 1 CARD 6 0 Ω G 0 0 0 0 1 0 0 CARD 7 0.0 0.0 0.0 0.0 CARD 8 103 103 CARD 9 MATERIAL ONE (PURE ABSORBER) CARD 1C 1.0 0.0 1.0 0.0 0.0 C.0 CARD 11 10.0 0.0 10.0 0.0 0.0 C.0 CARD 12 MATERIAL TWO CARD 13 0.1 0.2 1.0 1.0 0.5 C.0 CARD 14 5.0 10.0 10.0 0.0 4.0 C.4 CARD 15 10.0 1.03 CARD 16 22 0.0 30.03 CARD 17 2 3 13 CARD 18 1.0 0.0 0.8 0.2 1.0 C.0 CARD 19 3 CARD 2C 0.6 0.4 0.7 0.3 1.0 C.0 CARD 21 3 CARD 22 1000.0 1.03 CARD 23 3 3 33 CARD 24 0 1 23 CARD 25 0.0 0.5 0.53 CARD 26 1.0 . 95 .85 . 6 • 3 .2 CARD 27 .15 .14 .13 .12 .114 .1 CARD 28 3 CARD 29 13 CARD 3 C 13 CARD 31 30 10 3 C 0 0 2 0.001 CARD 32 -1 CARD 33 4 0.13 CARD 34 30 30 3 C 0 0 2 1.0 CARD 35 10 30 30 1 0 3 1.0 CARD 36 CARD 37

### 

Cards 19 and 20 contain the fission fractions for fissions caused by neutrons of group one for each coarse-mesh interval. Cards 21 and 22 contain the same information for fissions caused by neutrons of group two. Group velocities are entered on card 23. Cards 24 through 26 contain the mixture numbers, mixture commands, and mixture densities, respectively. Cards 27 through 29 contain the space-dependent material densities. Cards 30 and 31 contain the activity material numbers and the activity crosssection positions. Card 32 contains the information necessary to define the first time zone. This card specifies that 30 time steps be taken, printing every tenth step and dumping after 30 steps. Frequency extrapolation and group-dependent time step sizes are not used. The activities and the flux moments are to be printed and the time step size is 0.001. Card 33 indicates that new material densities are to be read. These densities are on card 34. Cards 35 and 36 define two successive time zones. Note that the frequency extrapolation option is selected in the final time zone. The problem input is terminated with a blank card. Further problems may be entered at this point.

All of the code output for this sample problem is shown in the appendix. The first page of the output contains the heading, title information, and a list of the control integers and floating point parameters. All the input arrays are listed on output pp. (1), (2), (3), and (4). Output p. (5) shows a schematic map of the system that indicates the material in each coarse-mesh zone, radii, number of fine intervals in each coarse zone, and boundary conditions. The boundary conditions are indicated by the numbers forming the left and right boundaries of the diagram.

Following the system map is a list of the mixture tables and the mixed cross sections. The coarse-mesh and fine-mesh geometries are then described, followed by a fission fractions listing. The initial condition is printed on output p. (7). This print is controlled by the value of the integer IEDOPT, which is equal to 2 in this problem. This integer is also entered on the time zone cards so that the output edit may be changed if desired. For this sample problem, the collided flux is initially zero so that the total flux equals the uncollided flux. The uncollided flux is the average of the uncollided flux over the mesh cell indicated. The first time zone card is printed on output p. (8). The results of the execution of the time zone card are printed on output pp. (9), (10), and (11) in the same format as the initial condition. On output p. (11) a message is printed indicating that the requested restart dump was made successfully.

Since the next time zone card contains a negative number in the first position (see card 33 of Table XVI), the code attempts to read the new arrays selected on card 7 of Table XVI. Because ITDEN is the only nonzero parameter on this card the material density is the only new array read by the code. The new densities are printed on output p. (12); another new time zone card is read and printed on output p. (13), with the resultant output printed on output p. (14). The final time zone card is printed on output p. (15). Note that the frequency extrapolation option is selected and that the output indicator IEDOPT is changed so that the frequencies are printed. These frequencies appear on output pp. (16), (17), and (18). It is interesting to note that the frequencies appear to converge to a single number for late times.

### ACKNOWLEDGMENT

The TIMEX code is based largely on the steadystate program ONETRAN that was written by K. D. Lathrop.

### REFERENCES

- B. G. Carlson and K. D. Lathrop, "Transport Theory - The Method of Discrete Ordinates," in <u>Computing Methods in Reactor Physics</u>, Greenspan, Kelber, and Okrent, Eds., (Gordon and Breach, New York 1968), Chap. III, p.171.
- K. D. Lathrop, "DTF-IV A FORTRAN-IV Program for Solving the Multigroup Transport Equation with Anisotropic Scattering," LA-3373, Los Alamos Scientific Laboratory (1965).
- Wm. H. Reed and K. F. Hansen, "Alternating Direction Methods for the Reactor Kinetics Equations," Nucl. Sci. Eng. <u>41</u>, 431 (1970).
- W. H. Reed, "The Effectiveness of Acceleration Techniques for Iterative Methods in Transport Theory," Nucl. Sci. Eng. <u>45</u>, 245 (1971).

DNE OR MORE OF THE FCLLOWING CONCITICNAL ARRAYS MAY BE LOAOGO AT EACH TIME ZONE.\*\*\*\*\* 0\*ND/1.cruss sections 0\*ND/1.sources NUMBER OF MATERIALS FRCM LIBRARY NUMBER OF MATERIALS FRCM LIBRARY NUMBER OF MIXTURE INSTRUCTIONS ROL OF TOTAL CRCSS SECTICA LAST ROL OF SCIES SECTICA AND OF SELF SCATTER CRCSS SECTICA AND VES SPACE OFFEWIGHT MATERIAL CENSITY O/1 NO/YES SPACE OFFEWIGHT MATERIAL CENSITY O/1 NO/YES SPACE OFFEWIGHT MATERIAL CENSITY O/1 NO/YES SECTICA O/1 NO/YES SIGTICATH CRCBR ANISGTRCPIC SOURCE O/1 NO/YES SIGTICATHS OUNCE O/1 NO/YES SIGTICATHS OUNCE O/1 NO/YES SIGTI SOURCE O/1 NO/YES SIGN FRACTICON/YEN SOURCE O/1 NO/YEN SOURCE O/1 NO/YEN SOURCE O/1 NO/YEN SIGN FRACTICON/YEN SOURCE O/1 NO/YEN SOUR volubles of groups NUMBER OF GROUPS NUMBER OF COARSE MESH INTERVALS NUMBER OF COARSE MESH INTERVALS LEFT/RIGHT BOUNDARY CONDITION-0/1/2/3/4 VACUW/REFLECTIVE/PERICIC/WHITE/ALBEOD T ORL 5 STATIAG OFTICNS ISEE MANUAL) O THRU 5 SOURCE INPUT CPTIONS ISEE MANUAL) O THRU 5 SOURCE INPUT CPTIONS ISEE MANUAL) 1/2/3 PLANE/CYLINDER/SPHERE 1-PN MANO MU,2-OPN MANC MU,3-READ MANO MU TOTAL NUMBER OF MATERIALS 10/7/71 NDRMALLZATION APPLITUDE BUCKLING HEIGHT IN CP. BUCKLING WIOTH IN CM. TIME ISECCNOS) AFTER WHICH DUMP TAKEN OIRECT/ADJCINT ISOTROPIC/NTH CROER ANISOTROPIC 0,NO/1,COARSE PESH BCUNDARLES 0,NO/1,CROSS SECTION IOEATLFICATION 0,NO/1,FISSION SPECTRUP 0,NO/1,VELOCITIES THIS TIMEX PROBLEM RUN CN 03/23/72 WITH VERSION Sample problem Instantaneous point burst in Sphere 0,ND/1,PITTRE INSTRUCTICNS 0,ND/1,0ENSITY FUNCTION 0,ND/1,LEFT ALBEOC FACTORS 0,ND/1,RIGHT ALBEOC FACTORS DUTPLT E0IT OPTICA RESTART TIME STEP NUMHER 0/1 NO/YES PLOT FINAL FLUX NUMHER OF ACTIVITIES SN ORDER ۳ Q 1% 70 BWTH T IMOFF \*\*\*\* ITIOXS ITFISS ITVEL ITVEL I TOEN I TL800 I TR800 I START IQOPT IGEOM IQUAD MT IE OOP T ITN IPLUT IACT NORM 8 HG T 1 T X S 1 T 0 1 T B 1 TH 1 SC T 1 SN 1 SN 1 GM 1 BL 1 BL MTP MCR ЯN 0000000 400004 N00-0 2 ŝ ÷ 00 0 a æ ....

(1)

2

.

2

INPUT FINE & MESH

1904 WORDS OF CORE REQUIRED I 27000 ALLOWED) 1131 Hords of Extended Core Required Iequal to 000003 CCTAL THOUSAND, with 000300 octal thousand Allowed)

### ANGULAR CCEFFICIENTS

м	POINT WEIGHT	LEVEL WEIGHT	NU CRISINE	MURAR COSINE	WGT*MU	BETA PLUS	8ETA MINUS
1	5.061427E-02	5.061427E-02	-9.602899E-01	-9.602899E-01	-4.860437E-C2	9.6C2899E-C1	0.
2	1.111905E-01	1.111905E-01	-7.965665E-01	-7.966665 -01	-8.858176E-C2	1.233793E+CC	4.371289E-01
3	1.568533E-01	1.568533E-01	-5.253324E-01	-5.255324E-01	-8.24315CE-C2	1.4CC146E+CG	8.746141E-01
4	1.813419E-01	1.813419E-01	-1.834346E-01	-1.834346E-01	-3.326439E-02	1.3945C4E+CC	1.211C6SE+00
5	1.813419E-01	1.813419E-01	1.834346E-01	1.834346E-01	3.326439E-02	1.211C69E+CC	1.394504E+00
6	1.569533E-01	1.568533E-01	5.255324E-01	5.255324E-01	8.24315CE-02	8.746141E-C1	1.4C0146E+00
7	1.111905E-01	1.111905E-01	7.966665E-01	7.966665E-01	8.858176E-02	4.371269E-C1	1.233793E+00
8	5.061427E-02	5.061427E-02	9.602899E-01	9.602899E-01	4.860437E-02	с.	9.602899E-01

.

.

.

SPHERICAL HARMONIC FUNCTIONS

I SOTROPIC

(2)

~

•

•

1	.100000E+01
2	.100000E+01
3	10CC00E+01
4	.100000E+01
5	.100C00E+01
6	.100000E+01
-	1000005-01

7 .100000E+01 8 .100000E+01

MAT ND 1 2		LOAOED FRCM CAROS Loaded From Caros	CARO CROSS SECTION INPUT SECTION Material one (pure Absorber) Material two
INPUT CROSS SECT	1		

GROUP 1 GROUP 2 .100000E+01 .100000E+02 1 2 0. 0. .100000E+01 -100000E+02 3 0. 4 0. 0. 5 0. 0. 6 0. INPUT CROSS SECT 2 GRUUP 1 GROUP 2 .5C00C0E+01 1 -100C00E+00 .1C00C0E+02 2 +200000E+00 .100000E+02 +100000E+01 3 .100C00E+01 0. 4 •500000E+00 .400000E+01 5 6 0. .400000E+00

INITIAL CONDITION

.

.

ප

UNCOLLIGEO FLUX

INPUT ENERGY SHAPE 2 1.0000E+01 1.0000E+00

INPUT SOURCE FOR GROUP 1

ISUTROPIC COMPONENT SOURCE ZERO EVERYMHERE

INPUT SOURCE FUR GROUP 2

ISOTROPIC COMPONENT Source Zero Everywhere

.

INPUT COARSE MESH 4 0. 1.0000E+01 2.0000E+01 3.0000E+01 INPUT CROSS SEC IO 3 2 3 1 INPUT FISSN G SPEC 6

.

```
INPUT VELOCITIES
                                  2
1.0000E+03 1.0000E+00
INPUT MIX NUMBERS
                                   3
                3
                                                      3
                                   3
INPUT MIX COMMANDS
                                   3
                                                      2
                0
                                   1
INPUT MIX DENSITY
                               3
  0.
                     5.0000E-01 5.0000E-01
INPUT R DENSITY
                                 30
 1.0000E+00 9.5000E-01 8.5000E-01 6.0000E-01 3.0000E-01 2.0000E-01 1.5000E-01 1.400CE-01 1.3C00E-01 1.2000E-01
1.1000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.00CCE-01 1.0CCCE-01 1.CC00E-01 1.0000E-01
1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.000CE-01 1.0CCCE-01 1.CC00E-01 1.0000E-01
INPUT ACT MAT NO.S
                                   1
                1
INPUT ACT XS POS
                                  1
                1
```

٠

.

R M COLU <del>M</del>	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	111111 0 1 0 0 111111 • 30. 0 0 10 3	M IS NUMBER OF FINE	INT ERVALS IN E	ACH COARSE INTERVAL
MIXTUR	RE NUMBER MIXTURE	COMMAND MATERI	AL ATOMIC DENSITY		
	3	0	0. 5.000000F-01	1	
	3	2	5.0000000E-01	3	
GROUP MIXEO 1 2 3 4 5 6	NUMBER 1 X-SECT MATERL 3 .550000E+00 .10000E+01 .50000E+00 .250000E+00 .250000E+00 .250000E+00				
GROUP	NUMBER 2				
MIXEO	X-SEC T				
	MATERL 3				
1	•7500C0E+01				
2	• 500000E+01 100000E+02				
5	• 100000E+02				
5	.200000E+01				
6	+200000E+00				
		COARSE MESH	GECMETRY		
	NO. OF INTERVA	LS WIDTH	FINE MESH SIZE	LEFT BOUNDARY	

•

· .

•

٠

1 2 3 4	ND. OF INTERVALS 10 10 10 0	WIDTH .10000000E+02 .10000000E+02 .10000000E+02 C.	+10000000E+01 +10000000E+01 +10000000E+01 0+	0+ •100000000E+02 •20000000E+02 •30000000E+02
------------------	---	--	---	--

•

.

(5)

•

•

34

\$

### FINE WESH GEOMETRY

	COAR SE MESH	LEFT BOUNDARY	AVERAGE RACIUS	VOLUME	LEFT AREA
1	- 1	0.	•20000000E+00	•41887902E+01	0.
2	1	.1000000E+01	1500000E+01	.29321531E+02	837759C4E+C1
3	1	20000000E+01	•25000000E+01	•79587014E+02	• 50265482E+C2
4	1	.3000000E+01	.3500000E+01	15498524E+03	1C890855E+C3
5	1	.400000005+01	•45000000E+01	25551620E+03	20106193E+03
6	1	.50000000E+01	•55000000E+01	•38117991E+03	.3C997C48E+C3
7	ī	.6000000E+01	.6500000E+01	•23197636E+03	•45238934E+C3
8	ī	.70000000E+01	.7500000E+01	•70790554E+03	•01156337E+C3
ý,	1	.8000000E+01	.85000000E+01	•90896747E+03	8C424772E+C3
10	1	.9000000E+01	.95000000E+01	11351621E+04	1C136972E+C4
11	2	-1000000E+02	.10500000E+02	13864896E+04	12566371E+C4
12	2	-11000000E+02	+11500000E+02	16629497E+04	15163421E+C4
13	2	.1200000E+02	.12500000E+02	.19645426E+04	18C95574E+C4
14	z	.13000000E+02	.13500000E+02	.22912682E+04	21195276E+C4
15	2	1400000E+02	•14500000E+02	.26431260E+04	24630CE65+C4
16	2	15000000E+02	15500000E+02	•30201177E+04	• 28232446E+C4
17	2	16000000E+02	.1650000E+02	.34222416E+04	.321699C9E+C4
18	2	.1700000E+02	.17500000E+02	.38494982E+04	.36274923E+C4
19	2	180000007+02	•18500000E+02	43018875E+04	•40715C41E+C4
20	2	1900000E+02	.19500000E+02	•47794096E+04	.4532271CE+C4
21	3	•200000002+02	.20500000E+02	•2820644E+04	• 5C265482E+C4
22	3	2100000E+02	2150000E+02	•5%098520E+04	•553752C7E+C4
23	3	.22000000E+02	22500000E+02	•63627723E+04	•6CE21234E+C4
24	3	230000002+02	23500000E+02	69408254E+04	•66434213E+C4
25	3	24000000E+02	24500000E+02	•75440112E+04	•72382295E+C4
26	3	•25000005+02	25500000E+02	•81723297E+04	•78497928E+C4
27	3	+2600000E+02	26500000E+02	88257810E+04	.84948665E+C4
28	3	27000000E+02	27500000E+02	•95043650E+04	•91566954E+C4
29	3	.28000000E+02	+28500000E+02	10208082E+05	.98520346E+C4
30	3	2 9000000E+02	29500000E+02	10936931E+05	1C564129E+C5
31	· 0	.3000000E+02	0.	0.	11309734E+C5

3

UNALTERED FISSION FRACTIONS FOR GRCUP 1

GROUPS BY ROWS 1 ZONE 2 ZCNE ZONE 1 1 .100000E+01 2 0. .8C00C0E+00 .100000E+01 .2000C0E+00 0.

UNALTERED FISSION FRACTIONS FOR GRCUP 2

GROUPS BY ROWS 1

.

ZONE 2 ZONE 3 ZONE 1

1 .600000E+00 .700000E+00 .100000E+01 2 .400000E+00 .3000C0E+00 0.

•

.

•

ы С

٠.

TIME STEP NUMBER =	0 R	EAL TIME = 0.		TIME STEP SI	ZE = 0.	
FLUXES FOR GROUP	1					
UNCOLLIDED FLUX IS	238732E+04	AT MESH INTERVAL	1			
COMPONENT NO. 1						
1 .238732E+04	2 0.	3 0.	4 0.	50.	6	0. 70.
8 0.	90.	10 0.	11 0.	12 0.	13	0. 14 0.
15 0.	16 0.	17 0.	18 0.	19 0.	20	0. 21 0.
22 0.	23 0.	24 0.	25 0.	26 0.	27	0. 28 0.
29 0.	30 0.					
FLUXES FOR GROUP	2					
UNCOLLIGED FLUX IS	.238732E+00	AT MESH INTERVAL	1			
COMPONENT ND. 1						
1 .238732E+00	2 0.	30.	4 0.	50.	6	0. 70.
8 0.	90.	10 0.	11 0.	12 0.	13	0. 14 0.
15 0.	16 0.	17 0.	18 0.	19 0.	20	0. 21 0.
22 0.	23 0.	24 0.	25 0.	26 0.	27	0. 28 0.
29 0.	30 0.					
ACTIVITIES		•				
1 1 .23897E+04	1 2 0.	1 3 0.	1 4	0.	1 5 0.	160.
1 7 0.	180.	190.	1 10	0.	1 11 0.	1 12 0.
1 13 0.	1 14 0.	1 15 0.	1 16	0.	1 17 0.	1 18 0.
1 19 0.	1 20 0.	1 21 0.	1 2 2	0.	1 23 0.	1 24 0.
1 25 0.	1 26 0.	1 27 0.	1 28	0.	1 29 0.	1 30 0.

•

.

٠

•

• •

### TIME ZUNE PARAMETERS

.

• .

.

NUMBER OF TIME STEPS = 30 NUMBER OF STEPS PER PRINT = 10 NUMBER OF STEPS PER OUMP = 30 FREQUENCY INDICATOR = 0 VARIABLE TIME STEP INDICATOR = 0 OUTPUT INOICATOR = 2 TIME STEP SIZE = .100000E-02

.

.

.

TIME STEP NUMBER = 10 REAL TIME = .100000E-01 TIME STEP SIZE = .1C0000E-02 FLUXES FOR GROUP 1 UNCOLLIGED FLUX IS .850777E-01 AT WESH INTERVAL 11 COMPONENT NO. 1 4 .144101E+01 7 .185076E+00 1 •141738E+02 2 •850987E+01 5 .594947E+CO 6 .330314E+00 3 .345835E+01 14 0. 8 .109320E+00 9 .615357E-01 10 .353009E-01 11 .101724E+00 12 0. 13 0. 21 0. 15 0. 16 0. 17 0. 18 0. 19 0. 20 0. 27 0. 28 0. 22 0. 23 0. 24 0. 25 0. 26 0. 29 0. 30 0. FLUXES FOR GROUP 2 UNCOLLIDED FLUX IS .216014E+00 AT MESH INTERVAL 1 COMPONENT NO. 1 4 .464571E-02 5 .73012CE-C3 6 .219563E-03 7 .798522E-04 1 •159792E+01 2 •169399E+00 3 •237585E-01 9 .199802E-04 10 .104695E-04 11 .493636E-06 12 0. 13 0. 14 0. 8 .399452E-04 15 0. 16 0. 17 0. 18 0. 19 0. 20 C. 21 0. 27 0. 28 0. 22 0. 23 0. 24 0. 25 0. 26 0. 29 0. 30 0. ACTIVITIES 1 1 •30153E+02 1 2 •10204E+02 1 3 •36959E+01 1 4 •14875E+01 1 5 •6C225E+00 1 6 •33251E+00 1 7 •18587E+00 1 8 •10972E+00 1 9 •61735E-01 1 10 •35406E-01 1 11 •1C173E+C0 1 12 0• 1 14 0. 1 15 0. 1 13 0. 1 16 0. 1 18 0. 1 17 0. 1 23 0. 1 24 0. 1 19 0. 120 0. 1 21 0. 122 0. 1 25 0. 1 26 0. 1 27 0. 1 28 0. 1 29 0. 1 30 0.

•

છ

۰.

.

•

.

TIME STEP SIZE = .1COOOCE-02 REAL TIME = .200000E-01 TIME STEP NUMBER = 20 FLUXES FOR GROUP 1 UNCOLLIDED FLUX IS .813376E-02 AT MESH INTERVAL 21 COMPONENT NO. 1 6 .133938E+00 7 .100119E+00 1 .268435E+01 2 .128720E+01 4 .298148E+00 5 .173368E+CO 3 .465693E+00 9 .639398E-01 10 .498847E-01 11 .377476E-01 12 .289925E-C1 13 .2264C7E-01 14 .174733E-01 8 .813797E-01 16 .986869E-02 17 .720682E-02 18 .516276E-02 19 .366631E-C2 20 .254281E-02 21 .970594E-02 15 .132523E-01 28 0. 26 0. 27 0. 24 0. 25 0. 23 0. 22 0. 30 0. 29 0. FLUXES FOR GROUP 2 .195458E+00 AT MESH INTERVAL 1 UNCOLLIDED FLUX IS COMPONENT ND. 1 7 .198335E-03 6 .4632C2E-03 5 .126042E-C2 3 .289437E-01 4 .683177E-02 2 .181165E+00 1 .159286E+01 11 .136586E-04 12 .836348E-C5 13 .567930E-05 14 .390947E-05 9 .721436E-04 10 .445513E-04 8 .121495E-03 16 .181891E-05 17 .122804E-05 18 .832836E-06 19 .559187E-C6 20 .3757C6E-06 21 0. 15 .265627E-05 28 0. 27 0. 25 0. 26 0. 23 0. 24 0. 22 0. 29 0. 30 0. 

 1
 1
 1
 1
 3
 .75513 E+00
 1
 4
 .36647E+0C
 1
 5
 .1E599E+00
 1
 6
 .13857E+00

 1
 1
 .10210E+00
 1
 8
 .82595E-01
 1
 9
 .64661E-01
 1
 10
 .50330E-01
 1
 11
 .37884E-C1
 1
 12
 .29077E-01

 1
 13
 .22698E-01
 1
 14
 .17512E-01
 1
 15
 .13279E-01
 1
 16
 .98869E-02
 1
 17
 .72191E-C2
 1
 18
 .51711E-02

 1
 19
 .36719E-02
 1
 20
 .25466E-02
 1
 21
 .97059E-02
 1
 22
 0.
 1
 23
 0.
 1
 24
 0.

 1
 19
 .36719E-02
 1
 21
 .70
 0
 1
 20
 .70
 0
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.
 1
 0.</td ACTIVITIES 1 29 0. 1 27 0. 1 28 0. 1 25 0. 1 26 0.

..

TIME STEP NUMBER =	30	REAL	TIME	:= ,	.300000 E-01	TIME	STEP	SIZE =	.1C0000E-02	
FLUXES FOR GROUP COMPONENT NO. 1	1					·				
1 .201522E+01	2	.744201E+00	3	.161138	3E+00 4	.841110E-01	5	.464335E-C1	6 • 371252E-01	7 .296622E-01
8 .257193E-01	9	.217266E-01	10	.182443	3E-01 11	-149658E-01	12	-126451E-C1	13 .11CC89E-01	14 .963684E-02
15 .944687E-02	16	.739540E-02	17	.644297	7E-02 18	.557091E-02	19	.4759EEE-C2	20 .396558E-02	21 .321391E-02
22 .259969E-02	23	.21C252E-02	24	.168027	7E-02 25	-132299E-02	26	-1C24E8E-C2	27 .775857E-03	28 • 582 562 E-03
29 .426358E-03	30	-305140E-03								
FLUXES FOR GROUP	2									
UNCULLIDED FLUX IS	<b>1</b>	L76857E+00 A1	MES	SH INTER	RVAL 1					
COMPONENT NO. 1										
1 +157203E+01	2	182413E+00	3	.292951	LE-01 4	•728713E-02	5	-137748E-C2	6 .537921E-03	7 .238739E-03
8 .155362E-03	9	.97C190E-04	10	.638858	3E-04 11	-206831E-04	12	-137361E-C4	13 .10C639E-04	14 .764517E-05
15 .571486F-05	16	.437977E-05	17	.329747	7E-05 18	251804E-05	19	-188956F-C5	20 .141C32E-05	21 0.
22 0.	23 (	0.	24 (		25	0.	26 0	•	27 0.	28 0.
29 0.	30 (	0.						•		
ACTIVITIES										
1 1 .17736E+02	1	2 .256B3E+0	1	1 3	.45409E+00	1 4 .1569	98E+0	0 1 5	.6C208E-01 1 6	•42504E-01
1 7 .32050E-01	1	8 .27273E-0	)1	1 9	.22697E-01	1 10 .1888	33E-0	1 1 11	.15173E-C1 1 12	.12782E-01
1 13 .11110E-01	1	14 .97133E-0	2	1 15	.85040E-02	1 16 .7439	26-0	2 1 17	.64759E-C2 1 18	• 55 961 E-02
1 19 .47788E-02	1	20 .39841E-0	)2	1 21	.32139 E-02	1 22 .2599	7E-0	2 1 23	.21025E-C2 1 24	•16803E-02
1 25 .13230E-02	1	26 .10249E-0	2	1 27	.77990E-03	1 28 .5825	6E-0	3 1 29	.42636E-03 1 30	.30514E-03

.

.

\*\*\*\*\*\*\*\* OUMP WRITTEN CN UNIT 7 AT TIME STEP NUMBER 30 \*\*\*\*\*\*\*\*\*

- -

•

•

•

•

.

THE FOLLOWING INPUT WAS READ AT THE END OF TIME STEP 30

INPUT R DENSITY 30 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.000CE-C1 1.00CCE-01 1.CC00E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.000CE-C1 1.0CCCE-01 1.CC00E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.0000E-01 1.000CE-C1 1.0CCCE-01 1.CC00E-01 1.0000E-01

41

.

TIME ZONE PARAMETERS

.

NUMBER OF TIME STEPS = 30NUMBER OF STEPS PER PRINT = 30NUMBER OF STEPS PER OUMP = 30FR SQUENCY INDICATOR = 0VARIABLE TIME STEP INDICATOR = 0OUTPUT INOICATOR = 2TIME STEP SIZE = .100000E+01

.

.

٠

.

•

....

ТІМЕ	ST	EP NUMBER =	60	REAL	TIME	= .	.300300	DE+02		T IME	STEP	SIZE =	.10000	E+01		
FLUXE	S	FOR GROUP	1													
COMPO	)N E	NT ND. 1														
1	•	134133E-02	2	121555E-02	3	.10658	1E-02	4	.91792	9E-03	5	.759291E-C	36	•616585E-03	7	.488318E-03
8	•	382674E-03	9	•293654E-03	10	.21961	4E-03	11	+15089	4E-03	12	.116567E-C	3 13	.885211E-04	14	.687372E-04
15	•	541444E-04	16	•431344E-04	17	.34576	2E-04	18	.27816	0E-04	19	.2234C5E-C4	20	-176726E-04	21	-137127E-04
22	•	1077808-04	23	.867711E-05	24	.704810	6E-05	25	.57627	9E-05	26	.473942E-C	5 27	.391612E-05	28	.324998E-05
29	•	270692E-05	30	•226242E-05												
FLUXE	S	FOR GROUP	2													
COMPO	NE	NT ND. 1														
1	•	229534E-02	2	•201740E-02	3	.165962	2E-02	4	.12934	1E-02	5	•944142E-C	36	•661163E-03	7	.44647_E-03
8	•	295469E-03	9	•187874E-03	10	.10218	6E-03	11	.35782	26-04	12	.11601CE-C4	13	.654254E-05	14	.394734E-05
15	•	301339E-05	16	•223017E-05	17	.18078	5E-05	18	.13969	9E-05	19	.110548E-C	5 20	•683246E-06	21	.182094E-06
22	•	293331E-07	23	•762303E-08	24	.21228	6E-08	25	.61606	3E-09	26	.184965E-C	27	•569C66E-10	28	-178769E-10
29	•	570938E-11	30	185507E-11												
ACTIV	/ I T	IES														
1	1	.24195E-01	1	2 .21390E-	01	1 3	.17662	2E-01	1 4	•138	52E-0	1 1 5	.1C2C1E	-01 1 6	.7228	2E-02
1	7	•49531E-02	1	8 .33374E-	02	19	.21724	+E-02	1 10	•124	15E-0	2 1 11	.51672E	-03 1 12	.2325	86-03
1 1	13	15395E-03	1	14 .10821E-	03	1 15	.84278	3E-04	1 16	•654	36E-0	4 1 17	.52655E	-C4 1 18	.4178	6E-04
1 1	9	.33395E-04	1	20 .24505E-	04	1 21	.15534	+E-04	1 2 2	.110	71E-0	4 1 2 3	.87533E	- C5 1 24	.7069	4E-05
1 2	25	•57690E-05	1	26 .47413E-	05	1 27	.39167	7 E 05	1 28	• 325	025-0	5 1 2 9	.27070E	-C5 1 30	• 22 62	4E-05

•

1

.

.

\*\*\*\*\*\*\* OUMP WRITTEN ON UNIT 7 AT TIME STEP NUMBER 60 \*\*\*\*\*\*\*\*

(14)

•

• •

•

.

TIME ZONE PARAMETERS

.

NUNBER OF TIME STEPS = 30 NUMBER OF STEPS PER PRINT = 10 NUMBER OF STEPS PER OUMP = 30 FR:GUENCY INDICATOR = 1 VARIABLE TIME STEP INDICATOR = 0 OUTPUT INDICATOR = 3 TIME STEP SIZE = .1000C0E+01

.

.

•

TIME STEP NUMBER =	70 REAL	IME =	•400300E+0	2	TIME STEP	SIZE =	+1CCC00E+01	
FLUXES FOR GROUP 1								
1 •103+02E-03 4	2 .153741E-03	3 .1425	14E-03 4	•130727E-	03 5 📲	1163\$8E-C	3 6 .101168E-03	7 .852424E-04
	9 • 55 68816-04	.0 .4166	54E-04 11	•301878E-	04 12 .:	219636E-C4	4 13 .164834E-04	14 .126866E-04
	• • /85806E-05	7 .6271	43E-05 18	•502896E-	05 19 .4	403CC2E-C	5 20 .318641E-05	21 .247589E-05
	3 •156904E-05	4 +1274	616-05 25	•104219E-	05 26 .	657117E-C	5 27 .7C8212E-06	28 •284426-06
	0 .409120E-06							
1 = 2051015 + 00 = 3								
	2 - 1778585+00	3 20020	01E+00 4	196764E+	00 5	192511E+C	0 6188211E+00	7183955E+00
15 - 1777455+00 14	7 = 1780645400	0 -1/640	52E+00 11	175981E+	00 12:	176311E+C	D 131769C3E+00	14177346E+00
	3 - 1799745400	1 -1103	226+00 15	178515E+	00 19	178665E+CC	20178762E+00	21178803E+00
29 - 1790565+00 30	3 - 1700765+00	41/89	156+00 25	178950E+	00 26	178581E+C(	27 -•179CC9E+00	28179034E+00
	0 -•1190182+00							
COMPONENT NO. 1								
1 .247473E-03 2	2 .232925F-03	3 21221	115-03 4	1074245				
8 .752786F-04 9	9 5166365-04 1	0 29213	275-04 11	+10/0340-		1592536-03	6 .130C81E-03	7 .101650E-03
15 .674756E-06 16	6 472984E-06 1	7 .37507	75-06 19	-100040	14 12 .:	48641E-C	13 •177123E-05	14 •954566E-06
22 788557E-08 23	3 223436F-08	4 .71118	13E-09 25	2220265-	0 19 .4	2236476-68	20 •13/559E-06	21 • 392500E-07
29 •241567E-11 30	0 .77C338F-12	• • • • • • • • •		•2323350	J7 20 •1	1242246-10	J 27 .241((5E-10	28 •759425E-11
FREQUENCIES FOR GROUP	2							
122550CE+00 2	2221414E+00	321517	70E+00 4	207409E+	10 5 - 1	977696+00		7 . 1771075.00
81678496+00 9	916C149E+00 1	0 - 15513	B1E+00 11	151391E+	12 - 1	497676400		
15163139E+00 16	5 168345E+00 1	717108	9E+00 18	172684F+	19 - 1	737016+00	20 - 172700 + 00	14 = .1375702+00
22 172307E+00 23	3175889E+00 2	417553	39E+00 25	155848F+	26 - 1	183266+00	27 - 9069676 - 01	21 - 1752100+00
29849127E-01 30	0820413E-01							200002176-01
ACTIVITIES								
1 1 •26381E-02	1 2 .24830E-02	1 3	•22657E-02	1 4	20071E-02	15	-17093E-02 1 6	-14020E-02
1 7 •11017E-02	1 8 .82258E-03	19	.57172E-03	1 10	33379E-03	1 11	-13683E-C3 1 12	-568285-04
1 13 •34196E-04	1 14 .22232E-04	1 15	-16667 E-04	1 16	12588E-04	1 17	-1CC22E-C4 1 18	-78798F-05
1 19 .62605E-05	1 20 .45620E-05	1 21	-28684E-05	1 2 2	20273E-05	1 23	-15914E-C5 1 24	12817F-05
1 25 .10445E-05	1 26 .85788E-06	1 27	.70845E-06	1 28	58781F-06	1 29	-46953E-06 1 30	400135-04

/ \*

.

- •

NPONENT ND. 1						
1 •229093E-04 2 •21	7632E-04 3 .204	699E-04 4 .	190730E-04 5	•173356E-C4	6 .153950E-04	7 •132588E-04
8 •110608E-04 9 •88	5948E-05 10 .675	854E-05 11 •	491502E-05 12	•357352E-C5	13 •267553E-05	14 .205527E-05
15 •160408E-05 16 •12	6895E-05 17 .101	156E-05 18 .	810398E-06 19	•€48915E-C6	20 .512740E-06	21 •398182E-06
22 .313220E-06 23 .25	2128E-06 24 •204	750E-06 25 .	167370E-06 26	.137615E-C6	27 .113683E-06	28 •943256E-07
29 • 7854948-07 30 • 65	6398E-07					
EQUENCIES FOR GROUP 1	10055.00 0 101	2005.00				
	19852+00 3191	328E+00 4	190548E+00 5 -	-•189567E+C0	6188539E+00	7187493E+00
0 = 0.1000900 + 00 = 0.10000000000000000000000000000000	58765+00 10185	439E+00 11	1852258+00 12 -	185221E+CO	13 1853C6E+00	14 -•185382E+00
13 - 1054545400 - 10 - 10	57925+00 2/ 105	579E+00 18	1856246+00 19 -	185663E+CU	20 1856598+00	21 185/33E+00
22 - 100000000 - 20 - 100000000000000000	57835+00 24185	800E+00 25 -+.	1858156+00 26 -	185828E+CO	27185840E+00	28185850E+00
11XES ED9 C9010 2	58885+00					
1 310468F-04 2 29	8022E-04 3 .279	822E-04 4	2566615-04 5	2282605-04	6 1961695-06	7 1416965-04
8 1257705-04 9 90	0348E-05 10 524	240F-05 11	1962235-05 12	-654423F-CA	13 . 3292525-06	14 -173018F-06
15 .118779E-06 16 .81	C849E-07 17 .632	300F-07 18	474922F-07 19	-368855F-C7	20 .2266455-07	21 .6520326-08
22 .134427E-08 23 .38	4854E-09 24 .123	142E-09 25	406963E-10 26	-138115F-10	27 .477743E-11	28 .167816F-11
29 .595830E-12 30 .21	3758E-12					
SEQUENCIES FOR GROUP 2						
1 1981756+00 2 19	7207E+00 3195	759E+00 4:	193934E+00 5 -	191672E+C0	61852C3E+00	7186648E+00 '
8184308E+00 918	2294E+00 10180	848E+00 11:	179486E+00 12 -	178159E+CO	13178123E+00	14178951E+00
15180357E+00 1618	1698E+00 17182	723E+00 18	183417E+00 19 -	1839C3E+C0	20184111E+00	21183504E+00
22 181588E+00 23 18	C250E+00 24179	019E+00 25:	177663E+00 26 -	17624CE+C0	27174553E+00	28173038E+00
29172714E+00 3017	3488E+00					
CTIVITIES						
1 1 •33338E-03 1 2	•31979E-03 1 3	• 30029 E-03	1 4 •2 573E-0	0315.	24560E-C3 1 6	.21154E-03
1 7 •17494E-03 1 8	•13683E-03 1 9	•98894E-04	1 10 .59183E-0	04 1 11 .	24537E-C4 1 12	.10118E-04
1 13 •59680E-05 1 14	•37854E-05 1 15	•27919E-05	1 16 .20798E-0	05 1 17 .	16439E-C5 1 18	•12853E-05
1 19 .10178E-05 1 20	•73938E-06 1 21	•46339E-06	1 22 • 32666E-0	06 1 23 •	25598E-C6 1 24	•20598E-06
1 25 •16778E-06 1 26	•13775E-06 1 27	•11373E-06	1 28 •94342E-0	07 1 29 •	78555E-C7 1 30	•65642E-07

• •

(17)

•

.

• • ·

•

.

TIME STEP NUMBER =	90	REAL	TIME =	•	600300	E+02			TIME	STEP	SIZ	E =	•1CCC	0CE + 0	1				
FLUXES FOR GROUP	1																		
COMPONENT NO. 1	-																		
1 .340677E-05	2.	324382E-05	3.3	06107	E-05	4	-286	327 F	-05	5	-261		5 6	. 23	3300	E-05	7	2020336	-05
8 .169271E-05	9.	136047E-05	10 .1	04001	8-05	11	.757	102F	-06	12	-550	475E-C	< 13	- 41	1588	E-06	14	3163696	-05
15 •246831E-06	16 .	195205E-06	17 .1	55570	E-06	18	.124	606F	-06	19	.997	5808-0	7 20	. 78	AC C 7	E-07	21	6110166	-07
22 .481278E-07	23 .	387367E-07	24 3	14550	E-07	25	.257	104F	-07	26	.211	3 6 3 F - C	7 27	.17	46131	E-07	28	1449745	-07
29 .12063EE-07	30 .	10C808E-07							••					•••	40231		20	• • • • • • • • • •	01
FREQUENCIES FOR GRO	UP	1																	
1189622E+00	2	189510E+00	31	89352	E+00	4 -	189	166F	+00	5 -	-188	9756+0	) 6	18	8657	F+00	7		
8188256E+00	9	188097E+00	101	88001	E+00	11 -	187	953E	+00	12 -	187	952F+C		- 18	7970	E+00	14	187 9866	+00
15183002E+00	16	188015E+00	171	88027	E+00	18 -	- 188	036E	+00	19 -	188	C45E+C	20	18	8053	E+00	21	-1880626	+00
22188068E+00	23	188073E+00	241	88077	E+00	25 -	188	081E	+00	26 -	188	C 8 4 F + C	27	-18	8026	E+00	28	188089F	+00
24188041E+00	30	188092E+00												•••			20	• • • • • • • • • •	
FLUXES FOR GROUP	2																		
COMPONENT ND. 1																			
1 •449389E-05	2.	432591E-05	3.4	09223	E-05	4	.378	859E-	-05	5	.340	7 8 CE- C	56	.29	64231	E-05	7	-247381E	-05
8 .194582E-05	9.	14C618E-05	10.8	24286	E-06	11	.310	504E-	-06	12	.104	213E-C	5 13	. 52	4644	E-07	14	-274811E	-07
15 .187501E-07	16 .	127238E-07	17 .9	87324	E-08	18	.7 39	018E-	-08	19	.572	477E-C	3 20	.35	1368	-08	21	-101425E	-08
22 .211341E-09	23.	61 C1 4 7E - 1 0	24 .1	96796	E-10	25	•656	992E-	-11	26	.225	355E-1)	27	.78	83688	E-12	28	.280339E	-12
29 .100806E-12	30 .	365901E-13																	
FREQUENCIES FOR GRO	UP	2																	
1191061E+00	2	19C808E+00	31	90436	E+00	4 -	189	979E	+00	5 -	.1894	429E+C(	) 6	18	88488	E+00	7	188265E	+00
8 -•187749E+00	9	187315E+00	101	87010	E+00	11 -	186	723E	+00	12 -	.1864	442E+C(	) 13	18	641 OE	E+00	14	186545E	+00
15 186813E+00	16	187070E+00	171	87289	E+00	18 -	187	444E	+00	19 -	•187	566E+C(	) 2C	18	7 <b>61</b> 8E	+00	21	187442E	+00
22186886E+00	23	186424E+00	241	85947	E+00	25 -	185	359E	+00	26 -	•1846	574E+C(	) 27	18	3887E	E+00	28	183004E	+00
27 182C09E+00	30	18C916E+00																	
ACTIVITIES									_	_									
1 1 •48246E-04	1 .	2 .46503E-0	4 1	3	•43983	E-04	1	4	.4074	49E-0	4	15	• 36693	BE-C4	1	6	• 31 9	76E-04	
1 7 .26/58c-04	1	8 •21151E-0	4 1	9	.15422	E-04	1	10	•928	29E-0	5	1 11	•36621	LE-C5	1	12	• 15 9	26 - 05	
1 13 •93663E-06	11	4 •59118 <del>2</del> -0	5 1	15	•43433	E-06	1	16	• 322	44E-0	6	1 17	.25430	CE-C6	1	18	.198	51E-06	
1 19 •15701E-06	12	0 .11395E-0	5 1	21	•/1334	E-07	1	22	.502	41E-0	7	1 23	•3934	7E-C7	1	24	• 31 6	52E-07	
1 25 •25776E-07	12	• •21161E-0	1	27	• 17469	E-07	1	28	• 1449	906-0	7	1 29	•1206	DE-C7	1	30	+100	81E-07	

.

\*\*\*\*\*\*\*\* OUMP WRITTEN ON UNIT 7 AT TIME STEP NUMBER 90 \*\*\*\*\*\*\*\*

.

(18)

.

..

EE/rr:403(150)

THIS TIMEX PROBLEM RUN ON 03/23/72 WITH VERSION 10/7/71

.

ENO OF FILE ON INPUT UNIT. NO MORE PROBLEMS